

Solutions Manual

Second Edition

Field and Wave Electromagnetics

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JOHNSON-WILEY PUBLISHERS COMPANY

Reading, Massachusetts • Menlo Park, California • New York
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Chapter 4

Vector Analysis

- Ex 1.1
- $\vec{a} = \frac{\vec{r}}{r} = \frac{x\vec{e}_1 + y\vec{e}_2 + z\vec{e}_3}{\sqrt{x^2 + y^2 + z^2}} = \frac{1}{\sqrt{x^2 + y^2 + z^2}}(x\vec{e}_1 + y\vec{e}_2 + z\vec{e}_3)$
 - $|\vec{a} - \vec{b}| = |\vec{a}_x + \vec{a}_y + \vec{a}_z| = \sqrt{1^2 + 1^2 + 1^2} = \sqrt{3}$
 - $\vec{a} \cdot \vec{b} = 0 = 2(0 \cdot 0) + (-1) = -1$
 - $\vec{a}_y = \cos^2(\vec{a} \cdot \vec{b} \vec{e}_2) = \cos^2(\cos^{-1}(\sqrt{3}/2)) = \cos^2 \pi/6$
 - $\vec{a} \cdot \vec{a}_y = \vec{a} \cdot \frac{\vec{y}}{y} = \vec{a} \cdot \frac{1}{\sqrt{3}}(x\vec{e}_1 + y\vec{e}_2) = \frac{xy}{\sqrt{3}}$
 - $\vec{a} \cdot \vec{z} = -\vec{a}_z = -\vec{e}_3$
 - $\vec{a} \cdot (\vec{a} \times \vec{z}) = (\vec{a} \cdot \vec{z}) \cdot \vec{a} = -\vec{a}_z$
 - $\vec{z} \cdot (\vec{a} \times \vec{b}) \cdot \vec{z} = \vec{z} \cdot (\vec{z} \times \vec{b}) = \vec{z} \cdot \vec{0} = 0$
 $\vec{z} \cdot (\vec{b} \times \vec{z}) = \vec{z} \cdot (\vec{z} \times \vec{b}) = \vec{z} \cdot \vec{0} = 0$
 $\vec{z} \cdot (\vec{b} \times \vec{a}) = \vec{z} \cdot (\vec{a} \times \vec{b}) = \vec{z} \cdot \vec{a}_z = \vec{z} \cdot \vec{e}_3 = 1$

Ex 1.2 Let $\vec{c} = c_1\vec{e}_1 + c_2\vec{e}_2 + c_3\vec{e}_3$,

$$\text{where } c_1^2 + c_2^2 + c_3^2 = 1. \quad \textcircled{*}$$

$$\text{For } \vec{c} \perp \vec{a}: \vec{c} \cdot \vec{a} = 0 \implies c_1 - 2c_2 + 3c_3 = 0. \quad \textcircled{**}$$

$$\text{For } \vec{c} \perp \vec{b}: \vec{c} \cdot \vec{b} = 0 \implies c_1 + c_2 - 2c_3 = 0. \quad \textcircled{***}$$

Solving $\textcircled{*}$, $\textcircled{**}$, and $\textcircled{***}$ simultaneously, we obtain

$$c_1 = \frac{1}{\sqrt{11}}, \quad c_2 = \frac{2}{\sqrt{11}}, \quad c_3 = \frac{1}{\sqrt{11}},$$

$$\text{and } \vec{c} = \frac{1}{\sqrt{11}}(\vec{e}_1 + 2\vec{e}_2 + \vec{e}_3).$$

Ex 1.3 For $\vec{A} \perp \vec{B}$ everywhere, $\vec{A} \cdot \vec{B} = \begin{vmatrix} x_1 & x_2 & x_3 \\ x_1 & x_2 & x_3 \\ x_1 & x_2 & x_3 \end{vmatrix} = 0$,
which requires that $\frac{x_1}{x_2} = \frac{x_2}{x_3} = \frac{x_3}{x_1}$.

Ex 1 From $A \cdot B = A \cdot C$ we have $A \cdot (B-C) = 0$. $\textcircled{1}$
 From $A \cdot B = A \cdot C$ we have $A \cdot (B-C) = 0$. $\textcircled{2}$
 $\textcircled{1}$ implies $A \perp (B-C)$, and $\textcircled{2}$ implies $A \perp (B-C)$.

Since A is not a null vector, $\textcircled{1}$ and $\textcircled{2}$ cannot hold at the same time unless $(B-C)$ is a null vector. Thus, $B=C$, or $B=A$.

Ex 2 Expand $A \times (\beta B + \gamma C) = A \times (\beta B) + A \times (\gamma C)$,
 or $A \times B = \beta A \times B + \gamma A \times C$.
 $\therefore A = \frac{1}{\beta} (\beta A + \gamma A)$.

Ex 3 Position vector of the three corners:

$$\vec{r}_1 = x_1 \hat{i} + y_1 \hat{j}, \quad \vec{r}_2 = x_2 \hat{i} + y_2 \hat{j}, \quad \vec{r}_3 = x_3 \hat{i} + y_3 \hat{j}$$

Vectors representing the three sides of the triangle:

$$\vec{r}_{12} = \vec{r}_2 - \vec{r}_1 = x_2 \hat{i} - x_1 \hat{i} + y_2 \hat{j} - y_1 \hat{j},$$

$$\vec{r}_{23} = \vec{r}_3 - \vec{r}_2 = x_3 \hat{i} - x_2 \hat{i} + y_3 \hat{j} - y_2 \hat{j},$$

$$\vec{r}_{31} = \vec{r}_1 - \vec{r}_3 = x_1 \hat{i} - x_3 \hat{i} + y_1 \hat{j} - y_3 \hat{j}.$$

$$\therefore \vec{r}_{12} \cdot \vec{r}_{23} = 0. \quad \therefore \triangle r_1 r_2 r_3 \text{ is a right triangle.}$$

$$\therefore \text{Area of triangle} = \frac{1}{2} |\vec{r}_{12} \times \vec{r}_{23}| = 12.$$

Ex 4



$$\vec{r}_1 = \vec{r} + \vec{r}, \quad \vec{r}_2 = \vec{r} + \vec{r}.$$

$$\vec{r}_1 \cdot \vec{r}_2 = (\vec{r} + \vec{r}) \cdot (\vec{r} + \vec{r})$$

$$= \vec{r} \cdot \vec{r} + \vec{r} \cdot \vec{r} = 0$$

for a rhombus.

$$\therefore \vec{r}_1 \perp \vec{r}_2.$$

Ex. 11



Let A , B , and C denote the vertices of a triangle, and D and E be the midpoints of sides AB and AC , respectively. The following vector relations hold:

$$\vec{AD} = \frac{1}{2} \vec{AB}, \quad \vec{AE} = \frac{1}{2} \vec{AC}.$$

$$\begin{aligned} \vec{DE} &= \vec{AD} - \vec{AE} = \frac{1}{2} (\vec{AB} - \vec{AC}) \\ &= \frac{1}{2} \vec{BC}. \end{aligned} \quad \text{Q.E.D.}$$

Ex. 12 $\vec{a}_1 = a_1 \cos \alpha + \vec{a}_2 \sin \alpha,$
 $\vec{a}_2 = a_2 \cos \beta + \vec{a}_1 \sin \beta.$

a) $\vec{a}_1 - \vec{a}_2 = \cos(\alpha - \beta) = \cos \alpha \cos \beta + \sin \alpha \sin \beta,$

b) $\vec{a}_2 + \vec{a}_1 = \begin{vmatrix} a_1 & a_2 & 0 \\ \cos \beta & \sin \beta & 0 \\ \sin \alpha & \cos \alpha & 0 \end{vmatrix} = a_1 (\sin \alpha \cos \beta - \cos \alpha \sin \beta)$
 $= a_1 \sin(\alpha - \beta).$

$\therefore \sin(\alpha - \beta) = \sin \alpha \cos \beta - \cos \alpha \sin \beta.$

Ex. 13



$$\vec{a} + \vec{b} + \vec{c} = 0.$$

$$\vec{a} \times \vec{a} + \vec{a} \times \vec{b} + \vec{c} \times \vec{a}.$$

$$\vec{c} \times \vec{a} + \vec{c} \times \vec{b} + \vec{b} \times \vec{c}.$$

$$\vec{b} \times \vec{c} + \vec{b} \times \vec{a} + \vec{a} \times \vec{b}.$$

Algebraic relations:

$$a^2 \sin \alpha_2 = b^2 \sin \alpha_1 = c^2 \sin \alpha_3.$$

Hence,

$$\frac{a^2}{a^2 \sin \alpha_2} = \frac{b^2}{b^2 \sin \alpha_1} = \frac{c^2}{c^2 \sin \alpha_3} \quad \left(\frac{\text{dividing}}{\text{dividing}} \right)$$

Ex 1.1



$$P = (r \cos \theta, r \sin \theta)$$

$$(r \cos \theta - r) \cdot (r \cos \theta - r) + (r \sin \theta - r \sin \theta) = 0,$$

$$\therefore (r \cos \theta) = (r \cos \theta)$$

Ex 1.2 Consider line $L_1: a_1x + b_1y = c_1$, which has a slope equal to $-b_1/a_1$. Draw the normal line passing through the origin and parallel to L_1 as $L_2: a_2x + b_2y = 0$. The position vector of a point (x, y) on L_2 is

$$\vec{r} = a_2x + b_2y.$$

If we introduce the vector $\vec{N} = a_2\hat{i} + b_2\hat{j}$, we can write the equation of L_2 as

$$\vec{N} \cdot \vec{r} = 0.$$

Thus the vector \vec{N} is \perp to L_2 , and is normal to both L_1 and L_2 . It follows that the two lines L_1 and L_2 are perpendicular to each other if and only if their normal vectors \vec{N} and $\vec{N}' = a_1\hat{i} + b_1\hat{j}$ are orthogonal. This which implies

$$a_1a_2 + b_1b_2 = 0, \text{ or } \frac{a_2}{b_2} = -\frac{a_1}{b_1}.$$

That is, the slopes of lines L_1 and L_2 are the negative reciprocals of each other.

Ex 1.3 A) Letting the position vector of a point in the plane be

$$\vec{r} = a_1x + b_1y + c_1\hat{k}$$

and introducing the vector $\vec{N} = a_1\hat{i} + b_1\hat{j} + c_1\hat{k}$, we can write the plane equation as

$$\vec{N} \cdot \vec{r} = c_1 \quad (\text{constant}).$$

This shows that the projection of the position vector to any point in the plane at P is a constant, and that \vec{n} is a normal vector.

$$b) \quad d_n = \frac{|\vec{r}|}{|\vec{n}|} = \frac{\vec{r}_x \vec{n}_x + \vec{r}_y \vec{n}_y + \vec{r}_z \vec{n}_z}{\sqrt{\vec{n}_x^2 + \vec{n}_y^2 + \vec{n}_z^2}}$$

c) The perpendicular distance from the origin to the plane is

$$d_n = \vec{r} = \frac{a}{|\vec{n}|}$$

For our case, $a = 8$, $|\vec{n}| = \sqrt{3^2 + 4^2 + 5^2} = 7$,
and $d_n = \vec{r} = 8/7$.

Ex 10

$$\vec{r}_1 = -\vec{r}_y \hat{j} - \vec{r}_z \hat{k}, \quad \vec{\sigma}_1 = -\vec{r}_y \hat{j} + \vec{r}_z \hat{k}$$

$$\vec{r}_2 = \vec{r}_x (\cos \phi) + \vec{r}_y (\sin \phi) \hat{j} + \vec{r}_z \hat{k} = \vec{r}_x \frac{1}{2} + \vec{r}_y \frac{\sqrt{3}}{2}$$

$$\vec{\sigma}_2 = \vec{r}_2 - \vec{r}_1 = \vec{r}_x \frac{1}{2} + \vec{r}_y \frac{\sqrt{3}}{2} - \vec{r}_z \hat{k}, \quad |\vec{\sigma}_2| = \sqrt{3}$$

$$\vec{r}_1 \cdot \vec{\sigma}_2 = \vec{r}_1 \cdot \frac{\vec{\sigma}_2}{|\vec{\sigma}_2|} = \frac{\vec{r}_1 \cdot \vec{\sigma}_2}{\sqrt{3}} = 1/2$$

Ex 11

$$a) \quad x = r \cos \phi = \frac{r}{2} \cos(2\omega t) = \frac{r}{2} \cos \theta$$

$$y = r \sin \phi = \frac{r}{2} \sin(2\omega t) = \frac{r}{2} \sin \theta$$

$$z = a$$

$$b) \quad \dot{x} = (-r\omega \sin \theta) = (-a\omega \sin 2\omega t) = -a\omega \sin \theta$$

$$\dot{y} = (r\omega \cos \theta) = (a\omega \cos 2\omega t) = a\omega \cos \theta$$

$$\dot{z} = 0 = 2a\omega \sin \theta$$

Ex 12

$$a) \quad \vec{r}_1 = \vec{r}_x \frac{1}{\sqrt{2}} + \vec{r}_y \frac{1}{\sqrt{2}}$$

$$\vec{\sigma}_1 = \frac{1}{2} \left(\frac{1}{\sqrt{2}} \hat{j} - \frac{1}{\sqrt{2}} \hat{k} \right) = \frac{1}{2\sqrt{2}} (\hat{j} - \hat{k})$$

$$b) \quad \vec{r}_2 = \frac{1}{\sqrt{2}} (\vec{r}_x + \vec{r}_y), \quad \vec{\sigma}_2 = \frac{1}{2} (\hat{j} \cos \theta - \hat{k} \sin \theta)$$

$$c) \quad \vec{r}_1 \cdot \vec{\sigma}_2 = \frac{1}{2\sqrt{2}} (\hat{j} \cdot \hat{j} \cos \theta - \hat{j} \cdot \hat{k} \sin \theta) = \frac{1}{2} \cos \theta$$

Ex. 10 $\vec{F}_1 = \vec{F}_1 \cos \theta \cos \phi + \vec{F}_2 \sin \theta \cos \phi + \vec{F}_3 \sin \theta \sin \phi = \frac{F_1 \cos \theta \cos \phi}{\sqrt{\cos^2 \theta \cos^2 \phi + \sin^2 \theta \cos^2 \phi + \sin^2 \theta \sin^2 \phi}}$
 $\vec{F}_2 = \vec{F}_2 \cos \theta \cos \phi + \vec{F}_2 \sin \theta \cos \phi + \vec{F}_3 \sin \theta \sin \phi = \frac{F_2 \sin \theta \cos \phi}{\sqrt{\cos^2 \theta \cos^2 \phi + \sin^2 \theta \cos^2 \phi + \sin^2 \theta \sin^2 \phi}}$
 $\vec{F}_3 = -\vec{F}_3 \sin \theta \phi + \vec{F}_3 \cos \theta \phi = \frac{F_3 \sin \theta \sin \phi}{\sqrt{\cos^2 \theta \cos^2 \phi + \sin^2 \theta \cos^2 \phi + \sin^2 \theta \sin^2 \phi}}$

Ex. 11

- (i) $\vec{F}_1 \cdot \vec{F}_2 = \cos \theta$, (ii) $\vec{F}_1 \cdot \vec{F}_3 = \sin \theta \cos \phi$, (iii) $\vec{F}_2 \cdot \vec{F}_3 = \sin \theta \sin \phi$
 (iv) $\vec{F}_1 \cdot \vec{F}_3 = \sin \theta$, (v) $\vec{F}_2 \cdot \vec{F}_3 = \sin \theta \cos \phi$, (vi) $\vec{F}_1 \cdot \vec{F}_2 = \cos \theta$
 (vii) $\vec{F}_1 \cdot \vec{F}_3 = \sin \theta \sin \phi$, (viii) $\vec{F}_2 \cdot \vec{F}_3 = \sin \theta$, (ix) $\vec{F}_1 \cdot \vec{F}_2 = \cos \theta$

Ex. 12 $\vec{F} \cdot d\vec{l} = [F_x xy + F_y (y^2 - x^2)] \cdot (dx \hat{i} + dy \hat{j})$
 $= xy dx + (y^2 - x^2) dy$

(i) Along straight path (1). The equation of (1) is $y = x + 1$.

$$\int_{\text{path (1)}} \vec{F} \cdot d\vec{l} = \int_{x=0}^1 [xy dx + (y^2 - x^2) dy]$$

$$= \int_0^1 \frac{1}{2} (x+1)^2 dx + \int_0^1 (x+1 - x^2) dy$$

$$= 0.25 + 0.75 = 1.0$$

(ii) Along path (2). This path has two straight line segments. From (1) to (2) $x=0, dy=0, \vec{F} \cdot d\vec{l} = 0$. From (2) to (1) $y=0, dx=0, \vec{F} \cdot d\vec{l} = 0$. Hence,

$$\int_{\text{path (2)}} \vec{F} \cdot d\vec{l} = \int_0^1 (0 - x^2) dx + \int_0^1 x dx = 0 - 0.5 + 0.5 = 0.$$

Path (2) $\int \vec{F} \cdot d\vec{l} = 0$ because closed loop is not conservative.

Ex. 13 $\int_C \vec{F} \cdot d\vec{l} = \int_C (y dx + x dy)$

Let $u = xy, du = (y dx + x dy), \int_C \vec{F} \cdot d\vec{l} = \int_C du = \int_0^1 (1) dy = 1$

$$b) \text{ as } x_1 = 1, \text{ so } dx_1 = 0, \int_C \vec{F} \cdot d\vec{r} = \int_C (1 dx_2 + x_2 dx_3 - x_1 dx_1) = \int_C (1 dx_2 + x_2 dx_3)$$

Equal line integrals along two specific paths do not necessarily imply a conservative field. \vec{F} is a conservative field in this case because $\nabla \times \vec{F} = 0$ ($x_1 = 1$).

Ex 11

$$\begin{bmatrix} \vec{r}_1 \\ \vec{r}_2 \end{bmatrix} = \begin{bmatrix} \cos \theta & \sin \theta \\ \cos \theta & \sin \theta \end{bmatrix} \begin{bmatrix} \vec{r}_1 \\ \vec{r}_2 \end{bmatrix} = \begin{bmatrix} \cos \theta & \sin \theta \\ \cos \theta & \sin \theta \end{bmatrix} \begin{bmatrix} r \cos \theta \\ r \sin \theta \end{bmatrix}$$

$$\vec{r}_1 = r_1 \cos \theta \hat{i} + r_2 \sin \theta \hat{j}$$

$$\vec{r}_2 = r_1 \sin \theta \hat{i} + r_2 \cos \theta \hat{j}$$

$$\nabla \cdot \vec{r}_1 = \frac{\partial}{\partial x} (r_1 \cos \theta) + \frac{\partial}{\partial y} (r_2 \sin \theta) = r_1 (-\sin \theta) + r_2 (\cos \theta) = 0$$

There is no change in r ($r=1$) from \vec{r}_1 to \vec{r}_2 .

$$\therefore \int_C \vec{F} \cdot d\vec{r} = r^2 \int_{\cos \theta}^{\sin \theta} \cos \theta \sin \theta d\theta = 100$$

$$\text{Ex 12} \quad a) \vec{r} = (x_1 \hat{i} + x_2 \hat{j} + x_3 \hat{k}) \Rightarrow \vec{r} = (r \cos \theta \hat{i} + r \sin \theta \hat{j} + r \hat{k})$$

$$= r_1 \left(\cos \theta \hat{i} + \sin \theta \hat{j} + \hat{k} \right) e^{it}$$

$$(\vec{r} \cdot \vec{r})_t = - (x_1 \hat{i} + x_2 \hat{j} + x_3 \hat{k}) e^{it} = - (r_1 \cos \theta \hat{i} + r_1 \sin \theta \hat{j} + r_1 \hat{k}) e^{it}$$

$$b) \vec{r} = -x_1 \hat{i} - x_2 \hat{j} - x_3 \hat{k} \quad \vec{r}_{\text{new}} = \frac{1}{\sqrt{2}} (x_1 \hat{i} + x_2 \hat{j} + x_3 \hat{k})$$

$$\therefore (\vec{r} \cdot \vec{r})_t = \vec{r}_{\text{new}} = \frac{1}{\sqrt{2}} \left(\frac{r}{\sqrt{2}} + \frac{r}{\sqrt{2}} \right) e^{it} = 100 e^{it}$$

Ex 13 On the surface of the sphere, $r = R$.

$$\int_C (x_1 \cos \theta - x_2) \cdot d\vec{r} = \int_0^{2\pi} \int_0^\pi (R \cos \theta \cos \phi - R \sin \phi) R^2 \sin \phi d\phi d\theta$$

$$= \int_0^{2\pi} \int_0^\pi R^3 \cos \theta \sin \phi \cos \phi d\phi d\theta = 0$$

Ex 14 The first step is to find the equation for the unit normal $\vec{n}_1 = x_1 \hat{i} + x_2 \hat{j} + x_3 \hat{k}$ to the plane surface. This gives four corner points of the surface and the following four equations



Curve (A,B) $\int_0^1 x \, dx = \frac{1}{2} \quad \textcircled{a}$

Curve (B,C) $\int_0^1 x \, dx = \frac{1}{2} \quad \textcircled{b}$

Curve (C,D) $\int_0^1 x \, dx = \frac{1}{2} \quad \textcircled{c}$

Curve (D,A) $\int_0^1 x \, dx = \frac{1}{2} \quad \textcircled{d}$

The direction vector satisfies the condition: $\int_C \mathbf{F} \cdot d\mathbf{r} = 0 \quad \textcircled{e}$

From $\textcircled{a}-\textcircled{d}$ we obtain $\int_C \mathbf{F} \cdot d\mathbf{r} = 0$, and $\text{curl} \mathbf{F} = 0$.

Thus, $\int_C \mathbf{F} \cdot d\mathbf{r} = \int_C (x_1 + x_2) \cdot d\mathbf{r}$ in contour
and $\int_C \mathbf{F} \cdot d\mathbf{r} = \int_C x \, dx = \frac{1}{2} (1+1) = 1$.

Ex. 106 In spherical coordinates, $\mathbf{F} = \frac{1}{r^2} \mathbf{e}_r = \frac{1}{r^2} \mathbf{e}_1$

at $\mathbf{r} = \frac{1}{2} \mathbf{e}_1 = \frac{1}{2} \mathbf{e}_1$, $\mathbf{e}_1 = \mathbf{e}_1$

$$\mathbf{F} \cdot \mathbf{e}_1 = \frac{1}{r^2} \mathbf{e}_1 \cdot \mathbf{e}_1 = \frac{1}{(1/2)^2} = 4$$

at $\mathbf{r} = \frac{1}{2} \mathbf{e}_2 = \frac{1}{2} \mathbf{e}_2$, $\mathbf{e}_2 = \mathbf{e}_2$

$$\mathbf{F} \cdot \mathbf{e}_2 = \frac{1}{r^2} \mathbf{e}_2 \cdot \mathbf{e}_2 = 4$$

Ex. 107 For radial vector $\mathbf{F} = x_1 \mathbf{e}_1$, $\mathbf{F} \cdot \mathbf{e}_1 = \frac{1}{2} \int_0^1 (x^2) \, dx = 0$

Using divergence theorem, we have

$$\frac{1}{2} \int_C \mathbf{F} \cdot d\mathbf{r} = \frac{1}{2} \int_V (\text{div} \mathbf{F}) \, dV = \frac{1}{2} (1) = \frac{1}{2}$$

Ex. 108 $\int_C \mathbf{F} \cdot d\mathbf{r} = \left(\int_{C_1} + \int_{C_2} + \int_{C_3} \right) \mathbf{F} \cdot d\mathbf{r}$

Top face ($z=4$): $\vec{A} = 4\hat{x}\hat{x} + 4\hat{y}\hat{y}$, $d\vec{A} = 4\hat{x}\hat{x}dydz + 4\hat{y}\hat{y}dydz$.

$$\int_{\text{top}} \vec{A} \cdot d\vec{A} = \int_{\text{top}} 8\hat{z}\hat{z}dydz = 8(2)(2) = 32\text{ units}.$$

Bottom face ($z=0$): $\vec{A} = 2\hat{x}\hat{x}$, $d\vec{A} = -4\hat{z}\hat{z}dydz$.

$$\int_{\text{bottom}} \vec{A} \cdot d\vec{A} = 0.$$

Side face ($x=0$): $\vec{A} = 2\hat{y}\hat{y} + 4\hat{z}\hat{z}$, $d\vec{A} = 4\hat{x}\hat{x}dydz$.

$$\int_{\text{side}} \vec{A} \cdot d\vec{A} = 2\hat{x}\hat{x} \int_{\text{side}} dydz = 2\hat{x}\hat{x}(2)(2) = 8\text{ units}.$$

$$\therefore \oint \vec{A} \cdot d\vec{A} = 32\text{ units} + 0 + 8\text{ units} = 40\text{ units}.$$

Or, $\vec{A}(x) = 2\hat{x}$, $\int_V (\nabla \cdot \vec{A}) dV = \int_0^2 \int_0^2 \int_0^4 (2) dx dy dz = 40\text{ units} = \oint \vec{A} \cdot d\vec{A}$.

Ex-12 $\vec{v} \cdot \vec{v} = \hat{x} \frac{d}{dt}(v\hat{x}) + \hat{y} \frac{d}{dt}(v\hat{y}) = 2v\hat{z}$.

$$\int_V \vec{v} \cdot \vec{v} dV = 2v \int_V dV = 2v(2)(2) = 8v\hat{z} = \oint \vec{A} \cdot d\vec{A}$$

Divergence theorem fails to hold because \vec{v} has a singularity inside the volume at $r=0$.

Ex-13 $\oint_V (\vec{v} \cdot \vec{v}) dV = \oint_V \frac{d}{dt} \vec{A} \cdot d\vec{A} \quad \text{Q}$

Referring to Fig. 3-22, we note that the areas on the opposite sides of a differential volume in cylindrical coordinates are the same in ϕ - and z -directions, but are different in the r -direction. Let us first evaluate the contribution to $\oint \vec{A} \cdot d\vec{A}$ of the inside cylindrical face. On the inside face:

$$\begin{aligned} \int_{\text{inside}} \vec{A} \cdot d\vec{A} &= \int_{\text{inside}} \hat{r}\hat{r} \cdot (-\hat{r}\hat{r}) dA = -\hat{r}\hat{r} \int_{\text{inside}} (A_r \hat{r} + A_\phi \hat{\phi} + A_z \hat{z}) \cdot \hat{r} dA \\ &= -\left[A_r r \hat{z} + A_\phi \frac{dr}{dt} \right]_{r=0} = -A_r r \hat{z} \Big|_{r=0} \end{aligned} \quad \text{Q}$$

On the outside face:

$$\int_{\text{outside face}} \vec{T} \cdot d\vec{A} = A_1 \left(\hat{x} + \frac{y}{R} \hat{y} - \hat{z} \right) \cdot \left(\hat{x} + \frac{y}{R} \hat{y} \right) dA \\ = \left[A_1 \left(x_1 + \frac{y^2}{R} \right) + \frac{y}{R} \frac{dA}{dy} \right]_{y_1, y_2} = R A_1 \pi \\ \text{Adding (3) and (4), we have} \quad \text{(5)}$$

$$\left[\int_{\text{top}} + \int_{\text{bottom}} \right] \vec{T} \cdot d\vec{A} = \left[A_2 + \frac{y}{R} \frac{dA}{dy} \right]_{y_1, y_2} \pi r^2 dy + R A_1 \pi \\ = \frac{d}{dy} \left(r^2 A_2 \right) \Big|_{y_1, y_2} \pi r^2 dy + R A_1 \pi \quad \text{(6)}$$

where $R A_1 \pi$ contains internal and higher powers of dy . Similarly, the sum of the contributions of the top and bottom faces (collectively sum = dV) is

$$\left[\int_{\text{top}} + \int_{\text{bottom}} \right] \vec{T} \cdot d\vec{A} = \frac{d}{dy} \left[\pi r^2 A_2 \right]_{y_1, y_2} = R A_1 \pi \quad \text{(7)}$$

where $R A_1 \pi$ contains internal and higher powers of dy . Similarly, the sum of the contributions of the top and bottom faces (collectively sum = dV) is

$$\left[\int_{\text{top}} + \int_{\text{bottom}} \right] \vec{T} \cdot d\vec{A} = \left(r \frac{dA}{dy} \right) \Big|_{y_1, y_2} = R A_1 \pi \quad \text{(8)}$$

where $R A_1 \pi$ contains internal and higher powers of dy .

Combining (5), (6) and (7) in (2), dividing by the negative and letting $dV = \pi r^2 dy = 0$, we get

$$\vec{T} \cdot \vec{x} = \frac{1}{r} \frac{d}{dy} (r^2 A_2) = \frac{d}{dy} \left(\frac{r^2 A_2}{r} \right) = \frac{dA_2}{dy}$$

where the subscript 2 has been dropped for simplicity.

Ex 2.11 a) $\vec{r} = x_2 \hat{y}_2^2$, $d\vec{r} = x_2^2 dx_1 dy_1$.

$$\oint_C \vec{r} \cdot d\vec{r} = \int_0^1 \int_0^1 (x_2^2 - y_2^2) dx_1 dy_1 = 0.$$

b) $\vec{r} = x_1 \hat{x}_1$, $d\vec{r} = x_1^2 dx_1 dx_2 dy_1$.

$$\oint_C \vec{r} \cdot d\vec{r} = \int_0^1 \int_0^1 \int_0^1 (x_1^2 - x_2^2) dx_1 dx_2 dy_1 = 0.$$

Ex 2.12 $\vec{r} = x_1 x_2^2 \hat{x}_1 - x_2^2 x_1^2 \hat{x}_2$, $d\vec{r} = x_2^2 dx_1 + 2x_1 x_2 dx_2$.



$$a) \oint_C \vec{r} \cdot d\vec{r} = \int_C (x_2^2 dx_1 - x_1^2 dx_2)$$

$$\text{Path } \textcircled{a} \rightarrow \text{Path } \textcircled{b}: \int_0^1 x_2^2 dx_1 = x_2^2$$

$$\text{Path } \textcircled{b} \rightarrow \text{Path } \textcircled{c}: \int_0^1 -x_1^2 dx_2 = -\frac{1}{3}$$

$$\text{Path } \textcircled{c} \rightarrow \text{Path } \textcircled{d}: \int_0^1 x_2^2 dx_1 = x_2^2$$

$$\therefore \oint_C \vec{r} \cdot d\vec{r} = 1 + \frac{2}{3} - 1 = \frac{2}{3}$$

b) $\vec{r} = -x_2 x_1^2 \hat{x}_1$, $d\vec{r} = -x_2 dx_1 dy_1$.

$$\oint_C \vec{r} \cdot d\vec{r} = 0 \int_0^1 dx_1 \int_0^1 x_2^2 dy_1 = 0$$

Ex 2.13 $\oint_C \vec{r} \cdot d\vec{r} = (\vec{r} \cdot \vec{a})_2 = \frac{1}{2} \frac{1}{a_2} \left(\oint_C \vec{r} \cdot d\vec{r} \right)$ ①



where $a_2 = \vec{a} \cdot \vec{a}$ is given by

and the number equals
of the four sides (a,b,c,d).

Since, $d\vec{r} = \vec{a} dy_1$.

$$\vec{r} \cdot d\vec{r} = x_2^2 dx_1 + x_1^2 dx_2$$

where $x_2^2 dx_1 = \frac{1}{2} \frac{d}{dy_1} (x_1^2)$

$$= \frac{1}{2} \frac{d}{dy_1} (x_1^2) + \text{const}$$

$$\oint_C \vec{r} \cdot d\vec{r} = \left[x_1^2 - \frac{1}{2} \frac{d}{dy_1} (x_1^2) \right]_{y_1=0}^{y_1=1} = \text{const}$$

Solve 1: $\dot{x} = -x_2$ ($\dot{x}_1 = 0$), $\dot{x} = x_1$ ($\dot{x}_2 = 0$) $\Rightarrow \frac{dx_1}{dt} = 0$, $\frac{dx_2}{dt} = -x_1$

$$\int_{x_1(0)}^{x_1(t)} dx_1 = - \left[x_2 + \frac{t^2}{2} \right]_{x_2(0)} + x_2(0) \quad \text{①}$$

Combining ① and ②:

$$\int_{x_1(0)}^{x_1(t)} dx_1 = \left(- \frac{t^2}{2} + x_2(0) \right) \Big|_{x_2(0)} - x_2(0) \quad \text{③}$$

Solve 2: $\dot{x} = x_2$ ($\dot{x}_1 = 0$), $\dot{x} = x_1$ ($\dot{x}_2 = 0$) $\Rightarrow \frac{dx_1}{dt} = 0$, $\frac{dx_2}{dt} = x_1$

$$\int_{x_1(0)}^{x_1(t)} dx_1 = \left[x_2 + \frac{t^2}{2} \right]_{x_2(0)} + x_2(0) \Big|_{x_1(0)} - x_1(0) \quad \text{④}$$

Solve 3:

$$\int_{x_1(0)}^{x_1(t)} dx_1 = \left[x_2 + \frac{t^2}{2} \right]_{x_2(0)} - x_2(0) \Big|_{x_1(0)} - x_1(0) \quad \text{⑤}$$

Combining ③ and ⑤:

$$\int_{x_1(0)}^{x_1(t)} dx_1 = \frac{t^2}{2} \Big|_{x_2(0)} - x_2(0) + x_2(0) - x_1(0) + x_1(0)$$

$$= \frac{t^2}{2} (x_1(t) - x_1(0)) - x_1(0) + x_1(0) \quad \text{⑥}$$

Substituting ③, ④ and ⑤ in ⑥ we obtain:

$$(x_1 - x_1)_t = \frac{t^2}{2} \left[\frac{d}{dt} (x_1(t) - x_1) - \frac{d}{dt} \right] =$$

where the subscript t has been dropped for simplicity.

Solve 4: $\dot{x} = x_2$ ($\dot{x}_1 = 0$), $\dot{x} = -x_1$ ($\dot{x}_2 = 0$)

$$\int (x_1 - x_1)_t dt = \int_{x_1(0)}^{x_1(t)} dx_1 - \int_{x_2(0)}^{x_2(t)} dx_2 = x_1(t) - x_1(0) - x_2(t) + x_2(0) = 0$$

$$\int (x_2 - x_2)_t dt = \int_{x_1(0)}^{x_1(t)} dx_1 - \int_{x_2(0)}^{x_2(t)} dx_2 = x_1(t) - x_1(0) - x_2(t) + x_2(0) = 0$$

Solve 5: $\dot{x} = x_2$ ($\dot{x}_1 = 0$) + $\dot{x} = x_1$ ($\dot{x}_2 = 0$) + $\dot{x} = x_2$ ($\dot{x}_1 = 0$) + $\dot{x} = -x_1$ ($\dot{x}_2 = 0$)

a) \dot{x} (rotational) $\rightarrow \dot{x} + \dot{x} = 0$

$$\Rightarrow x_1 \left(\frac{dx_1}{dt} - \frac{dx_1}{dt} \right) + x_2 \left(\frac{dx_2}{dt} - \frac{dx_2}{dt} \right) + x_1 \left(\frac{dx_1}{dt} - \frac{dx_1}{dt} \right) + x_2 \left(\frac{dx_2}{dt} - \frac{dx_2}{dt} \right) = 0$$

which gives three equations:

$$\frac{\partial}{\partial x}(a + c_1 y + c_2 z) = \frac{\partial}{\partial x}(c_1 x - 2z) = 0 \implies c_1 + 0 = 0 \implies c_1 = 0$$

$$\frac{\partial}{\partial y}(a + c_1 y + c_2 z) = \frac{\partial}{\partial y}(c_1 x - 2z) = 0 \implies c_1 - 0 = 0 \implies c_1 = 0$$

$$\frac{\partial}{\partial z}(a + c_1 y + c_2 z) = \frac{\partial}{\partial z}(c_1 x - 2z) = 0 \implies c_2 = 0$$

∴ \vec{F} is conservative $\implies \vec{F} = \nabla \phi$.

$$\text{or } \frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} + \frac{\partial \phi}{\partial z} = 0.$$

$$\text{or } \frac{\partial}{\partial x}(a + c_1 y + c_2 z) + \frac{\partial}{\partial y}(c_1 x - 2z) + \frac{\partial}{\partial z}(c_1 x + c_2 y - c_3 z) = 0$$

$$\text{or } 1 + c_1 = 0 \implies c_1 = -1.$$

∴ $\vec{F} = -\nabla \phi \implies 2x(x+2) - 2y, 2z + c_2(c_1 y - 2z)$

$$= -c_1 \frac{\partial \phi}{\partial x} - c_2 \frac{\partial \phi}{\partial y} - c_3 \frac{\partial \phi}{\partial z}$$

$$\frac{\partial \phi}{\partial x} = -2x(x+2) \implies \phi = -\frac{x^2}{2} - 2x + f(c_1 y, z)$$

$$\frac{\partial \phi}{\partial y} = 2z \implies \phi = 2yz + f(c_1 y, z)$$

$$\frac{\partial \phi}{\partial z} = 2x + 2y + 2 \implies \phi = xz + 2yz + \frac{z^2}{2} + f(c_1 y)$$

$$\therefore \phi = -\frac{x^2}{2} + xz + 2yz + \frac{z^2}{2}$$

Chapter 4

Solutions of Electrostatic Problems

Ex 1. Use superposition of point or dipole distributions and air regions respectively. $\nabla^2 V = 0$ in both regions.

$$V_1 = a_1 x + a_2, \quad E_x = -a_1, \quad E_z = -a_2 \hat{z}$$

$$V_2 = a_3 x + a_4, \quad E_x = -a_3, \quad E_z = -a_4 \hat{z}$$

BC: at $y=0$, $V_1 = V_2$, at $y=0$, $E_x = E_2$
 at $y=a$: $V_1 = V_2$, $E_x = E_2$.

Solving: $a_1 = \frac{V_0}{2a}$, $a_2 = \frac{V_0}{2}$, $a_3 = \frac{V_0}{2}$, $a_4 = \frac{V_0}{2}$

(i) $E_x = -\frac{V_0}{2a}$, $E_z = -\frac{V_0}{2} \hat{z}$

(ii) $E_x = -\frac{V_0}{2a}$, $E_z = -\frac{V_0}{2} \hat{z}$

(iii) $E_x = -\frac{V_0}{2a}$, $E_z = -\frac{V_0}{2} \hat{z}$

(iv) $E_x = -\frac{V_0}{2a}$, $E_z = -\frac{V_0}{2} \hat{z}$

Ex 2. At a point where V is a maximum (minimum), the partial derivatives of V with respect to x, y and z would all be negative (positive), their sum could not vanish, as required by Laplace's equation.

Ex 3. Potential eq. $\nabla^2 V = -\frac{\rho}{\epsilon_0} \rightarrow \frac{1}{r} \frac{d}{dr} \left(r \frac{dV}{dr} \right) = -\frac{\rho}{\epsilon_0}$

Solution: $V = -\frac{\rho}{4\epsilon_0} r^2 + c_1 \ln r + c_2$

BC: at $r=a$, $V = \frac{\rho a^2}{2\epsilon_0}$, $c_1 = \frac{2\rho a^2}{\epsilon_0}$

at $r=b$, $V = -\frac{\rho b^2}{2\epsilon_0}$, $c_2 = \frac{2\rho a^2}{\epsilon_0} \ln \frac{a}{b}$

Ex 4



$$\oint \left(\epsilon_1 \frac{\partial V}{\partial x} \right)_{x=0} dx + \epsilon_2 \frac{\partial V}{\partial x} \Big|_{x=0} = \frac{\rho}{\epsilon_0} \int_{-a}^a dx$$

(i) $E_x = -\frac{\rho}{\epsilon_0} \int_{-a}^a dx$

(ii) $\int_{-a}^a E_x dx = -E_x a$

Ex. 11



Consider the conditions in the xy-plane (z=0).

a) $V_0 = \frac{1}{4\pi\epsilon_0} \left(\frac{1}{x} - \frac{1}{x'} + \frac{1}{y} - \frac{1}{y'} \right)$, where

$$x_1 = [(x-a)^2 + y^2 + d^2]^{3/2}, \quad x_2 = [(x+a)^2 + y^2 + d^2]^{3/2}$$

$$y_1 = [(x+a)^2 + (y-d)^2]^{3/2}, \quad y_2 = [(x+a)^2 + (y+d)^2]^{3/2}$$

$$\begin{aligned} E_x = -\nabla V_0 &= -E_{x1} \frac{\partial}{\partial x} - E_{x2} \frac{\partial}{\partial x} \\ &= -E_0 \frac{\partial}{\partial x} \left[-\frac{3x}{x_1^3} - \frac{3x}{x_2^3} - \frac{3y}{y_1^3} + \frac{3y}{y_2^3} \right] \\ &\quad + E_0 \frac{\partial}{\partial x} \left[-\frac{3x}{y_1^3} + \frac{3x}{y_2^3} - \frac{3y}{x_1^3} + \frac{3y}{x_2^3} \right]. \end{aligned}$$

E_x will have a z-component if the point P does not lie in the xy-plane.

b) On the conducting half-planes, $E_x = E_y = 0 = E_z$.

Along the x-axis, $E_x = \frac{1}{4\pi\epsilon_0} \left(\frac{1}{x^2} - \frac{1}{x'^2} \right) = E_z$.

and $E_y = \frac{1}{4\pi\epsilon_0} \left(\frac{1}{y^2} - \frac{1}{y'^2} \right) = 0$.

$$E_x = 0, \quad E_y = \frac{1}{4\pi\epsilon_0} \left(\frac{1}{y^2} - \frac{1}{y'^2} \right)$$

$$\begin{aligned} \therefore E(\text{int}) &= \frac{1}{4\pi\epsilon_0} \left\{ \frac{1}{(x-a)^2 + y^2 + d^2} - \frac{1}{(x+a)^2 + y^2 + d^2} \right\} \\ &= \begin{cases} 0, & \text{at } x=0, \\ \text{non-zero, at } x=d. \end{cases} \end{aligned}$$

Analogously for $E(\text{ext})$ on the vertical/conducting conducting plane by changing x to r and d to a .

Ex. 12 Refer to Example 4-4

$$E^{\text{ext}} = \frac{1}{4\pi\epsilon_0} \frac{2\lambda z}{(x^2 + y^2 + z^2)^{3/2}} = \frac{1}{2\pi\epsilon_0} \frac{\lambda z}{x^2 + y^2 + z^2} \quad (10a)$$

Ex. 11 From our C_{12} in problem 10-10

Ex. 12 (a) From Eqs. (10-18) and (10-19)

$$V_2 = \frac{Q_2}{4\pi\epsilon_0} \left[\frac{1}{r_2} + \frac{2Q_1}{r_2(r_2 - a)} \right]$$

$$E_r = -\hat{r}_2 \frac{dV_2}{dr_2} = -\hat{r}_2 \frac{d}{dr_2} \left[\frac{Q_2}{4\pi\epsilon_0} \left(\frac{1}{r_2} + \frac{2Q_1}{r_2(r_2 - a)} \right) \right]$$

A potential for our everywhere tangent to the electric field lines is obtained by integrating

$$\frac{dV}{dr} = \frac{E_r}{-1} = -\frac{dV_2}{dr_2}$$

which reduces to $\frac{dV}{dr} = \frac{dV_2}{dr_2} = \frac{d}{dr_2} \left[\frac{Q_2}{4\pi\epsilon_0} \left(\frac{1}{r_2} + \frac{2Q_1}{r_2(r_2 - a)} \right) \right]$

Integrating, we obtain $\int dV = \int \frac{d}{dr_2} \left[\frac{Q_2}{4\pi\epsilon_0} \left(\frac{1}{r_2} + \frac{2Q_1}{r_2(r_2 - a)} \right) \right] dr_2$

where K is a constant — choice of null V has arbitrary nature of C_1, C_2 .



$$V = \frac{Q_2}{4\pi\epsilon_0} \ln \frac{r}{a} + \frac{Q_1}{4\pi\epsilon_0} \ln \frac{r}{b}$$

Capacitance per unit length
 $C = \frac{Q}{V} = \frac{Q_2}{\frac{Q_2}{4\pi\epsilon_0} \ln \frac{r}{a} + \frac{Q_1}{4\pi\epsilon_0} \ln \frac{r}{b}}$

For equation:

$$\begin{aligned} Q_1 &= Q_2 \epsilon_1 & Q_2 &= Q_1 \epsilon_2 \\ Q_1 &= Q_2 \epsilon_1 & Q_2 &= Q_1 \epsilon_2 \end{aligned}$$

Let us obtain

$$\frac{dV}{dr} = \frac{Q_2}{4\pi\epsilon_0} \frac{1}{r} + \frac{Q_1}{4\pi\epsilon_0} \frac{1}{r} \quad \text{and} \quad Q_1^2 + Q_2^2 = Q^2 = Q_1^2 \epsilon_1^2 + Q_2^2 \epsilon_2^2 = Q^2$$

$$Q_1^2 = \frac{Q^2}{\epsilon_1^2} = \frac{Q^2}{\epsilon_1^2} - \frac{Q^2}{\epsilon_2^2} = \frac{Q^2 (\epsilon_2^2 - \epsilon_1^2)}{\epsilon_1^2 \epsilon_2^2 - \epsilon_1^2}$$

$$\begin{aligned} C &= \frac{Q}{\frac{Q_2}{4\pi\epsilon_0} \ln \frac{r}{a} + \frac{Q_1}{4\pi\epsilon_0} \ln \frac{r}{b}} \\ &= \frac{4\pi\epsilon_0 Q}{\ln \frac{r}{a} + \frac{\epsilon_1}{\epsilon_2} \ln \frac{r}{b}} \quad (17-10) \end{aligned}$$

Ex. 10.11 d_p (small) $v_p = \frac{d_p}{2}(\omega_p^2 - \omega^2 - \omega_0^2)$, d_p (large) $v_p = \frac{d_p}{2}(\omega_p^2 + \omega^2)$



d_p (small): $\omega^2 = \omega_p^2 - \omega_0^2$

d_p (large): $\omega^2 = \omega_p^2 + \omega_0^2$

$$\Rightarrow v = \frac{d_p}{2} \ln \left[\frac{\frac{d_p}{2}(\omega_p^2 - \omega_0^2) + \frac{d_p}{2}(\omega_p^2 + \omega_0^2)}{\frac{d_p}{2}(\omega_p^2 - \omega_0^2) - \frac{d_p}{2}(\omega_p^2 + \omega_0^2)} \right]$$

At $t=0$: $v = 0 = \frac{d_p}{2} \ln \left[\frac{\frac{d_p}{2}(\omega_p^2 - \omega_0^2) + \frac{d_p}{2}(\omega_p^2 + \omega_0^2)}{\frac{d_p}{2}(\omega_p^2 - \omega_0^2) - \frac{d_p}{2}(\omega_p^2 + \omega_0^2)} \right]$

At $t=t$: $v = 0 = \frac{d_p}{2} \ln \left[\frac{\frac{d_p}{2}(\omega_p^2 - \omega_0^2) + \frac{d_p}{2}(\omega_p^2 + \omega_0^2)}{\frac{d_p}{2}(\omega_p^2 - \omega_0^2) - \frac{d_p}{2}(\omega_p^2 + \omega_0^2)} \right]$

$$v - v_0 = \frac{d_p}{2} \ln \left[\frac{\frac{d_p}{2}(\omega_p^2 - \omega_0^2) + \frac{d_p}{2}(\omega_p^2 + \omega_0^2)}{\frac{d_p}{2}(\omega_p^2 - \omega_0^2) - \frac{d_p}{2}(\omega_p^2 + \omega_0^2)} \right]$$

Expressing ω_p^2 in terms of R and r

$$\text{and simplifying: } v - v_0 = \frac{d_p}{2} \ln \left[\left(\frac{R^2 + h^2}{R^2 - h^2} \right) \cdot \left(\frac{R^2 - h^2}{R^2 - r^2} \right) \right]^{1/2}$$

$$v - v_0 = \frac{d_p}{2} \ln \left[\frac{R^2 + h^2}{R^2 - h^2} \cdot \frac{R^2 - h^2}{R^2 - r^2} \right]^{1/2} = \frac{d_p}{2} \ln \left[\frac{R^2 + h^2}{R^2 - r^2} \right]^{1/2} \quad (10.11)$$

$$\Rightarrow \text{Time per oscillation } T = \frac{2\pi}{\omega} \ln \left[\frac{R^2 + h^2}{R^2 - r^2} \right]^{1/2} = \frac{2\pi d_p}{\omega} \ln \left[\frac{R^2 + h^2}{R^2 - r^2} \right]^{1/2} \quad (10.12)$$

Ex. 10.12



$$v_p = -\frac{d_p}{2} \omega, \quad \dot{v}_p = \frac{d_p}{2} \dot{\omega}$$

$$\Rightarrow \dot{v}_p = \frac{d_p}{2} \dot{\omega} \left(\frac{1}{\omega} - \frac{v_p}{\omega^2} \right)$$

$$\dot{v}_p = \frac{d_p}{2} \dot{\omega} \left(\frac{\omega - v_p}{\omega^2} \right)$$

$$\dot{v}_p = \frac{d_p}{2} \dot{\omega} \left(\frac{\omega + \omega_0}{\omega^2} \right)$$

$$\Rightarrow \dot{v}_p = -\frac{d_p}{2} \frac{\dot{\omega}}{\omega} \left[\frac{\omega + \omega_0}{\omega} \right] = -\frac{d_p}{2} \frac{\dot{\omega}}{\omega} \left[\frac{\omega + \omega_0}{\omega} \right]$$

Ex. 10.13 (See next page.)

Ex. 10.14 Suppose boundary conditions at end 1: $v = 0$, and at $x = \frac{d_p}{2} \ln \left[\frac{R^2 + h^2}{R^2 - r^2} \right]$

From Eq. 10.11 and the boundary conditions parts (a) and (b)

$$v = \frac{d_p}{2} \ln \left[\frac{R^2 + h^2}{R^2 - h^2} \cdot \frac{R^2 - h^2}{R^2 - r^2} \right]^{1/2}$$

$$v = \frac{d_p}{2} \ln \left[\frac{R^2 + h^2}{R^2 - r^2} \right]^{1/2}$$

In order to satisfy the b.c.'s at end 2, we require

$$\frac{d_p}{2} \ln \left[\frac{R^2 + h^2}{R^2 - r^2} \right]^{1/2} = \frac{d_p}{2} \ln \left[\frac{R^2 + h^2}{R^2 - r^2} \right]^{1/2} \Rightarrow \frac{d_p}{2} \ln \left[\frac{R^2 + h^2}{R^2 - r^2} \right]^{1/2} = \frac{d_p}{2} \ln \left[\frac{R^2 + h^2}{R^2 - r^2} \right]^{1/2}$$

Ex-16



1) Q_1 and system of image charges?

In left sphere

Charge system

$$Q_1 \text{ at } d_1 = a$$

$$-Q_1 \frac{a}{2a} \text{ at } d_1'$$

$$Q_2 = \frac{Q_1 a}{2a - a} \text{ at } d_2$$

$$-Q_2 \frac{a}{2a - a} = -\frac{Q_1 a}{2a - a} \text{ at } d_2'$$

$$Q_3 = \frac{Q_2 a}{2a - a} = Q_1$$

\vdots

$$Q_n = Q_1 \left(\frac{a}{2a - a} \right)^{n-1} \text{ at } d_n \quad Q_n = Q_1 \left(\frac{a}{2a - a} \right)^{n-1} \text{ at } d_n'$$

$$\left(\frac{a}{2a - a} \right)^{\infty} = 1 \quad \left(\frac{a}{2a - a} \right)^{\infty} = 1 \quad d_{\infty} = \frac{a}{2a - a} = 2a$$

$$1) C = \frac{Q_1}{V} = \frac{Q_1}{4\pi a^2} \left[1 + \sum_{n=1}^{\infty} \left(\frac{a}{2a - a} \right)^{2n} \right]$$

Ex-17 1) $V(x, y, z)$ - Required boundary conditions:



① $V(x, 0) = 0$ - Grounded conducting plane at $y=0$.

② $V(x, b) = 0$ - Grounded conducting plane at $y=b$.

③ $V(0, y) = \frac{V_0}{2} \left(1 - \frac{y}{b} \right)$ - Insulated plane at $x=0$.

④ $V(a, y) = \frac{V_0}{2} \left(1 + \frac{y}{b} \right)$ - Insulated plane at $x=a$.



2) $V(x, y, z)$ - Required boundary conditions:

① $V(x, y, 0) = 0$ - Grounded plane at $z=0$.

② $V(x, y, b) = 0$ - Grounded plane at $z=b$.

③ $V(0, y, z) = \frac{V_0}{2} \left(1 + \frac{z}{b} \right)$ - Insulated plane at $x=0$.

④ $V(a, y, z) = \frac{V_0}{2} \left(1 - \frac{z}{b} \right)$ - Insulated plane at $x=a$.

Ex. 11.11 $E_1 = 100 \text{ eV}$, $v_1 = \frac{1}{2}c$, $E_2 = 1000 \text{ eV}$, $v_2 = \frac{1}{2}c$



$$E_1 = \gamma m_0 c^2 = \frac{m_0 c^2}{\sqrt{1 - v_1^2/c^2}}$$

$$E_2 = \gamma m_0 c^2 = \frac{m_0 c^2}{\sqrt{1 - v_2^2/c^2}}$$

$$\frac{E_2}{E_1} = \frac{\sqrt{1 - v_1^2/c^2}}{\sqrt{1 - v_2^2/c^2}}$$

$$\frac{1000}{100} = \frac{\sqrt{1 - (1/2)^2}}{\sqrt{1 - v_2^2/c^2}}$$

$$10 = \frac{\sqrt{3/4}}{\sqrt{1 - v_2^2/c^2}}$$

$$\sqrt{1 - v_2^2/c^2} = \frac{\sqrt{3/4}}{10}$$

$$1 - v_2^2/c^2 = \frac{3}{400}$$

$$v_2^2/c^2 = 1 - \frac{3}{400} = \frac{397}{400}$$

$$v_2 = \frac{\sqrt{397}}{20} c$$

and simplifying: $v_2 = \frac{1}{20} c \sqrt{397}$

$$v_2 = \frac{1}{20} \times 3 \times 10^{10} \text{ cm/s} = 1.5 \times 10^9 \text{ cm/s}$$

$$\text{d) Force per unit length } F = \frac{2 \times 10^{-12} \text{ N/m}}{1 - (1/2)^2} = \frac{2 \times 10^{-12} \text{ N/m}}{3/4} = \frac{8}{3} \times 10^{-12} \text{ N/m}$$

Ex. 11.12



$$v_1 = \frac{1}{2}c, \quad v_2 = \frac{1}{3}c$$

$$\text{d) } \gamma = \frac{1}{\sqrt{1 - v^2/c^2}}$$

$$\gamma_1 = \frac{1}{\sqrt{1 - (1/2)^2}} = \frac{2}{\sqrt{3}}$$

$$\gamma_2 = \frac{1}{\sqrt{1 - (1/3)^2}} = \frac{3}{\sqrt{8}}$$

$$\text{e) } E = \gamma \frac{m_0 c^2}{\sqrt{1 - v^2/c^2}} = \frac{m_0 c^2}{\sqrt{1 - v^2/c^2}}$$

Ex. 11.13 (See next page.)

Ex. 11.14 Required boundary conditions at $x=0$: $V=0$, and $\psi \frac{d\psi}{dx} = 0$

From Ex. 11.10 and the boundary conditions, we have

$$\psi = \frac{A}{\sqrt{2\pi}} \left(e^{ik_1 x} + e^{-ik_1 x} \right) e^{-i\omega t}$$

$$\psi = \frac{A}{\sqrt{2\pi}} \left(e^{ik_1 x} + e^{-ik_1 x} \right) e^{-i\omega t}$$

In order to satisfy the $V=0$ and $\psi \frac{d\psi}{dx} = 0$ conditions, we require

$$\frac{d\psi}{dx} = ik_1 A \left(e^{ik_1 x} - e^{-ik_1 x} \right) e^{-i\omega t} = 0$$

Ex. 10



10) Q_1 and system of image charges:

<u>In left sphere</u>	<u>In right sphere</u>
Q_1 at $2a$ from O_1	$-Q_1 - \frac{a}{2a} Q_1$ at a
$Q_2 = \frac{2a}{2a - 2a} Q_1 = \infty$	$-Q_2 - \frac{a}{2a} Q_2 = \frac{2a}{2a - 2a} Q_1 = \infty$
$Q_3 = \frac{2a}{2a - 2a} Q_2 = \infty$	\vdots
$Q_n = Q_1 \left[\frac{2a}{2a - 2a} \right]^{n-1}$ at $2a$	$-Q_n - \frac{a}{2a} Q_n = \frac{2a}{2a - 2a} Q_1 = \infty$
$Q_{n+1} = \frac{2a}{2a - 2a} Q_n = \infty$	$Q = \frac{2a}{2a - 2a} Q_1 = \infty$

$$V = \frac{1}{4\pi\epsilon_0} \sum_{n=1}^{\infty} \left[\frac{Q_1}{r} + \frac{Q_2}{r} + \dots \right]$$

Ex. 11) $V(x, y, z)$, Required boundary conditions:



- 1) $V(x=0) = 0$ — Grounded conducting plane at $x=0$.
- 2) $V(x=a) = 0$ — Grounded conducting plane at $x=a$.
- 3) $V(x \rightarrow \pm\infty) = 0$ — $V(x) = \frac{Q}{4\pi\epsilon_0 r}$
- 4) Shape of potential boundary defined by:
 - 1) $V(x=0) = 0$ — $V(x) = \frac{Q}{4\pi\epsilon_0 r}$ at $x=0$ — $V(x) = \frac{Q}{4\pi\epsilon_0 r}$ at $x=0$
 - 2) $V(x=a) = 0$ — $V(x) = \frac{Q}{4\pi\epsilon_0 r}$ at $x=a$ — $V(x) = \frac{Q}{4\pi\epsilon_0 r}$ at $x=a$
- 5) $V(x \rightarrow \pm\infty) = 0$ — Required boundary condition:
 - 1) $V(x \rightarrow \pm\infty) = 0$ — $V(x) = \frac{Q}{4\pi\epsilon_0 r}$ at $x \rightarrow \pm\infty$
 - 2) $V(x \rightarrow \pm\infty) = 0$ — $V(x) = \frac{Q}{4\pi\epsilon_0 r}$ at $x \rightarrow \pm\infty$
 - 3) $V(x \rightarrow \pm\infty) = 0$ — $V(x) = \frac{Q}{4\pi\epsilon_0 r}$ at $x \rightarrow \pm\infty$
 - 4) $V(x \rightarrow \pm\infty) = 0$ — $V(x) = \frac{Q}{4\pi\epsilon_0 r}$ at $x \rightarrow \pm\infty$

Ex-12 $V(x,y) = C_1 \sinh \frac{x}{2} + C_2 \cosh \frac{x}{2}$

Ex-13 $V(x,y) = C_1 \sinh \frac{x}{2} + C_2 \cosh \frac{x}{2}$

$\frac{\partial V}{\partial x} = V_x = \sum_{n=1}^{\infty} C_n C_n(x,y) = \sum_{n=1}^{\infty} C_n \sinh \frac{x}{2} + C_n \cosh \frac{x}{2}$

$V(x,y) = \sum_{n=1}^{\infty} \frac{\sinh(\frac{x}{2}) + \cosh(\frac{x}{2})}{\sinh(\frac{x}{2}) - \cosh(\frac{x}{2})} C_n \sinh \frac{x}{2}$

Ex-14 $V(x,y) = \sum C_n \sin \frac{n\pi y}{a} = [C_1 \sinh \frac{x}{2} + C_2 \cosh \frac{x}{2}]$

At $y=0$, $V(x,0) = 0 = \sum C_n \sin \frac{n\pi \cdot 0}{a} \rightarrow C_1 = \left\{ \begin{array}{l} \frac{2C_2}{a} \text{ if } n \text{ is odd} \\ 0, \text{ otherwise} \end{array} \right.$

At $y=a$, $V(x,a) = 0 = \sum C_n \sin \frac{n\pi a}{a} = [C_1 \sinh \frac{x}{2} + C_2 \cosh \frac{x}{2}]$
 $\rightarrow C_1 \sinh \frac{x}{2} + C_2 \cosh \frac{x}{2} = \left\{ \begin{array}{l} \frac{2C_1}{a} \text{ if } n \text{ is odd} \\ 0, \text{ otherwise} \end{array} \right.$
 $\therefore C_2 = \left\{ \begin{array}{l} \frac{2C_1 \cosh(\frac{x}{2})}{\sinh(\frac{x}{2}) - \cosh(\frac{x}{2})} \text{ if } n \text{ is odd} \\ 0, \text{ otherwise} \end{array} \right.$

Ex-15 $V(x,y) = \sum \sum C_{nm} \sin \frac{n\pi x}{a} \sin \frac{m\pi y}{b} \sinh k_{nm} z$

where $k_{nm} = \sqrt{\left(\frac{n\pi}{a}\right)^2 + \left(\frac{m\pi}{b}\right)^2}$

At $z=0$, $V(x,y,0) = V_0 = \sum \sum C_{nm} \sin \frac{n\pi x}{a} \sin \frac{m\pi y}{b} \sinh k_{nm} z$
 $\rightarrow C_{nm} = \left\{ \begin{array}{l} \frac{V_0 \sinh k_{nm} z}{\sinh k_{nm} z} \text{ if } n, m \text{ is odd} \\ 0, \text{ otherwise} \end{array} \right.$

Ex-16 Solution: $V(x,y) = A_1 + A_2$

a) $A_1 = 0 \rightarrow A_1 = 0$
 $A_2 = 0 \rightarrow V(x,y) = A_2 \rightarrow A_2 = \frac{V_0}{2} \left. \begin{array}{l} \text{if } x=y \\ \text{otherwise} \end{array} \right\} \therefore V(x,y) = \frac{V_0}{2} A_2$

b) $A_1 = 0 \rightarrow V(x,y) = A_1 + A_2$
 $A_2 = 0 \rightarrow V(x,y) = A_1 + A_2 \rightarrow A_1 = -\frac{V_0}{2} \text{ if } x=y, A_2 = \frac{V_0}{2}$

$\therefore V(x,y) = \frac{V_0}{2} (2 - A_1) \text{ if } x=y$

Chapter 1

Steady Electric Currents

Ex. 1 a) Integrating $\epsilon_r(r) = \epsilon_0 \left(\frac{R}{r} \right)^{2n} = \frac{Q R^{2n}}{4\pi r^{2n}}$

$$\epsilon(r) = -\int \frac{Q R^{2n}}{r^{2n}} = -\frac{Q R^{2n}}{1-2n} \left(\frac{1}{r} \right)^{1-2n}$$

b) $\rho(r) = -\frac{d\epsilon(r)}{dr} = \frac{2n Q R^{2n}}{r^{2n+1}}$

$$Q = \int_0^R \rho(r) 4\pi r^2 dr = -\frac{2n Q R^{2n}}{1-2n} \int_0^R r^{-2n+2} dr = \frac{2n Q R}{1-2n}$$

c) On the inside, $r < R$, $E = -\epsilon(r) = \frac{Q R^{2n}}{4\pi r^{2n}}$

Total surface charge on inside $= Q_1 = \frac{2n Q R}{1-2n}$

Total charge on outside $= 0$

d) Substituting ϵ in Eq. (1-11)

$$u = \frac{\epsilon^2}{8\pi} = \left(\frac{Q R^{2n}}{4\pi r^{2n}} \right)^2 \frac{1}{8\pi} = \frac{Q^2 R^{4n}}{16\pi^2 r^{4n}}$$

Integrating $u = \left(\frac{Q^2 R^{4n}}{16\pi^2 r^{4n}} \right) 4\pi r^2$

\therefore Energy $U = \int_0^R \left(\frac{Q^2 R^{4n}}{4\pi r^{2n}} \right) dr$

For $n=0$ (i.e., dielectric $\epsilon = \epsilon_0$) $U = \frac{Q^2 R}{4\pi \epsilon_0}$

and $n=1$ (i.e., $\epsilon = \frac{Q R}{2\pi r}$) $U = \frac{Q^2 R \ln 2}{4\pi \epsilon_0} = \frac{Q^2 R \ln 2}{4\pi \epsilon_0}$

Ex. 2 $R_1 =$ Resistance per unit length of wire $= \frac{\rho}{A_1} = \frac{\rho}{\pi r_1^2}$

$R_2 =$ Resistance per unit length of coating $= \frac{\rho}{\pi r_2^2}$

Let $t =$ thickness of coating, $\rightarrow r_2 = r_1 + t$ (i.e., $r_2 - r_1 = t$)

a) $R_1 R_2 = \frac{\rho}{\pi} \left(\frac{1}{r_1^2} + \frac{1}{r_2^2} \right)$

b) $R_1 = R_2 = \frac{\rho}{\pi} \quad R = \frac{\rho}{\pi r_1^2} \quad R = \frac{\rho}{\pi r_2^2} = \frac{\rho}{\pi (r_1 + t)^2}$

$R_1 = \frac{\rho}{\pi} = \frac{\rho}{\pi r_1^2} \quad R = \frac{\rho}{\pi} = \frac{\rho}{\pi (r_1 + t)^2}$

Thus, $r_1 = r_1 + t$ and $R = R_1$

Ex 11.1 $I_1 = \sin(2t), I_2 = \sin(3t) \cos(t)$; $I_3 = \sin(2t) \cos(3t), I_4 = \sin(2t) \cos(4t)$
 $I_5 = \sin(2t) \cos(5t), I_6 = \cos(2t) \cos(3t)$; $I_7 = \cos(2t) \cos(4t), I_8 = \cos(2t) \cos(5t)$
 $I_9 = \sin(2t) \cos(4t), I_{10} = \sin(2t) \cos(5t)$. $\int I_1 = \frac{1}{2} I_2 = \frac{1}{2} \sin(4t)$

Ex 11.2 $I_1 = \sin(2t) \cos(3t), I_2 = \sin(3t) \cos(4t)$; $I_3 = \sin(2t) \cos(4t), I_4 = \sin(2t) \cos(5t)$
 $I_5 = \sin(3t) \cos(5t), I_6 = \sin(4t) \cos(5t)$; $I_7 = \cos(2t) \cos(3t), I_8 = \cos(2t) \cos(4t)$
 $I_9 = \cos(2t) \cos(5t), I_{10} = \cos(3t) \cos(4t)$

Ex 11.3 $I_1 = \frac{d}{dt} \left(\frac{e^{-2t}}{2} \right) = \frac{d}{dt} \left(\frac{e^{-2t}}{2} \right) = -e^{-2t} \cos(2t)$, $I = e^{-2t} \sin(2t)$

a) $I_1 = \int_0^1 \frac{d}{dx} \left(\frac{e^{-2x}}{2} \right) dx = \frac{e^{-2x}}{2} \Big|_0^1 = \frac{e^{-2}}{2} - \frac{1}{2}$
 b) $I_2 = \int_0^1 \frac{d}{dx} \left(\frac{e^{-2x}}{2} \right) dx = \frac{e^{-2x}}{2} \Big|_0^1 = \frac{e^{-2}}{2} - \frac{1}{2}$
 c) $I_3 = \int_0^1 \frac{d}{dx} \left(\frac{e^{-2x}}{2} \right) dx = \frac{e^{-2x}}{2} \Big|_0^1 = \frac{e^{-2}}{2} - \frac{1}{2}$
 $I_4 = \int_0^1 \frac{d}{dx} \left(\frac{e^{-2x}}{2} \right) dx = \frac{e^{-2x}}{2} \Big|_0^1 = \frac{e^{-2}}{2} - \frac{1}{2}$

Ex 11.4 a) $e^{-2t} \cos(2t) = \frac{1}{2} \cos(2t) \implies t = \frac{\cos(2t)}{2} = \cos(2t) \sin(2t)$

b) $I_1 = \int_0^1 \frac{d}{dx} \left(\frac{e^{-2x}}{2} \right) dx = \frac{e^{-2x}}{2} \Big|_0^1 = \frac{e^{-2}}{2} - \frac{1}{2} = \frac{1}{2} (e^{-2} - 1)$

$\therefore \frac{1}{2} (e^{-2} - 1) = \frac{1}{2} (e^{-2} - 1)$ Integration by parts
is not needed.

c) $I_2 = \int_0^1 \frac{d}{dx} \left(\frac{e^{-2x}}{2} \right) dx = \frac{e^{-2x}}{2} \Big|_0^1 = \frac{e^{-2}}{2} - \frac{1}{2} = \frac{1}{2} (e^{-2} - 1)$
Integration by parts is not needed.

Ex 11.5 a) $I = \frac{1}{2} \cos(2t) \implies t = \frac{1}{2} \cos(2t) = \cos(2t) \sin(2t)$

b) $I = \frac{1}{2} \cos(2t) = \frac{1}{2} \cos(2t)$

c) $I = \frac{1}{2} \cos(2t) = \frac{1}{2} \cos(2t)$

d) $I_1 = \frac{1}{2} \cos(2t)$ The given relation holds for all t (it will be that of a good solution).

$I_2 = \left(\frac{1}{2} \right)' - \left(\frac{1}{2} \right)'' = \left(\frac{1}{2} \right)' - \left(-\frac{1}{2} \right)'' = \left(\frac{1}{2} \right)' - \left(\frac{1}{2} \right)'' = \frac{1}{2} \cos(2t) = \frac{1}{2} \cos(2t)$
 $= \frac{1}{2} \cos(2t)$ (OK).

Ex-10) At E_1 (Normal): $E_{in} = E_{ref} \rightarrow E_1 \sin \alpha_1 = E_2 \sin \alpha_2$
 $E_1 \cos \alpha_1 = E_{tr} + E_{ref} \rightarrow E_1 \cos \alpha_1 = E_2 \cos \alpha_2 + E_1 \cos \alpha_1 + E_{ref}$
 $\therefore E_{ref} = E_1 \sqrt{\frac{\mu_1 \epsilon_1}{\mu_2 \epsilon_2}} \sin^2 \alpha_1$ (1)

$E_{tr} = E_1 - E_{ref} \rightarrow E_2 \sin \alpha_2 = E_1 \left(\frac{\mu_2 \epsilon_2}{\mu_1 \epsilon_1} \right)$ (2)

b) At E_2 (Normal): $E_{in} = E_{tr} = E_2 \rightarrow E_2 \cos \alpha_2 = E_2 \cos \alpha_2$

$E_2 = \left(\frac{\mu_1 \epsilon_1}{\mu_2 \epsilon_2} \right) E_1 = \left[\frac{\mu_1 \epsilon_1}{\mu_2 \epsilon_2} \right] E_1 \sin \alpha_1$

- c) If both media are perfect dielectrics, $\epsilon_1 > \epsilon_2$, $\mu_1 = \mu_2$.
 (1) and (2) reduce to $E_2 = E_1 \sin \alpha_1$ and $E_{ref} = E_1 \sin^2 \alpha_1$ respectively.

Ex-11



$E_{in} = E_1 = (V_0 - 0)/d$

At the leading edge of the dielectric, the electric field is constant in magnitude & directed vertically.

$E = E_1 \cos \alpha_1 = E_2 \cos \alpha_2 = E_2 \frac{d}{l}$

$E_2 = \sqrt{\left(\frac{l}{d} \right)^2 E_1^2} = \sqrt{\frac{l^2}{d^2} \left(\frac{V_0}{d} \right)^2} = \frac{l}{d} \frac{V_0}{d} = \frac{l V_0}{d^2}$

$E_1 = \frac{V_0}{d} = \frac{l V_0}{d^2} = \frac{l V_0}{d^2} \cos \alpha_2$

b) $E_1 \cos \alpha_1 = E_2 \cos \alpha_2 = \frac{l V_0}{d^2} \cos \alpha_2 = \frac{V_0}{d}$ on upper plate.

$E_1 \sin \alpha_1 = E_2 \sin \alpha_2 = \frac{l V_0}{d^2} \sin \alpha_2 = \frac{l V_0}{d^2} \frac{d}{l}$ on lower plate.

c) $E = E_1 \cos \alpha_1 = \frac{V_0}{d} \cos \alpha_1 = \frac{V_0}{d} \left[\frac{d}{l} \cos \alpha_2 \right] = \frac{V_0 \cos \alpha_2}{l}$

Ex-12



a) $V_1 = \frac{V_0}{2}$, $V_2 = \frac{V_0}{2}$

$V_3 = \frac{V_0}{2}$, $V_4 = \frac{V_0}{2}$

b) $P = V_1 I_1 = V_0^2 \frac{R_1}{R_1 + R_2}$

$= V_0^2 \frac{R_1 R_2}{R_1 + R_2}$

Ex-13 Refer to Fig. 1-6. In the transient state, the equation of continuity may be written at the interface.

$\frac{\partial \rho_{int}}{\partial t} + \nabla \cdot \mathbf{J} = \nabla \cdot \mathbf{J}' = \nabla \cdot \mathbf{J}''$

Now

$\nabla \cdot \mathbf{J} = \nabla \cdot \mathbf{J}' = 0$

$\nabla \cdot \mathbf{J}'' = \nabla \cdot \mathbf{J}''$

Solving ① and ② for x_1 and x_2 in terms of α and β :

$$x_1 = \frac{\beta(1-\alpha) + \alpha}{\beta(1-\alpha) + \alpha} \quad \text{③} \quad x_2 = \frac{\beta(1-\alpha) + \alpha}{\beta(1-\alpha) + \alpha} \quad \text{④}$$

(ii) Substituting ③ and ④ in ②:

$$-\frac{\beta}{\alpha} = \frac{\beta(1-\alpha) + \alpha}{\beta(1-\alpha) + \alpha} x_1 + \frac{\beta(1-\alpha) + \alpha}{\beta(1-\alpha) + \alpha} x_2 \quad \text{⑤}$$

Solution of ⑤:

$$x_1 = \left(\frac{\beta(1-\alpha) + \alpha}{\beta(1-\alpha) + \alpha} \right) [1 - \alpha^{-1}], \quad \text{⑥}$$

$$\text{where } T = \text{Substitution term} = \frac{\beta(1-\alpha) + \alpha}{\beta(1-\alpha) + \alpha} \quad \text{⑦}$$

(iii) Using ③ and ④:

$$x_1 = \frac{\beta(1-\alpha) + \alpha}{\beta(1-\alpha) + \alpha} (1 - \alpha^{-1}) = \frac{\beta(1-\alpha) + \alpha}{\beta(1-\alpha) + \alpha} \alpha^{-1}$$

$$x_2 = \frac{\beta(1-\alpha) + \alpha}{\beta(1-\alpha) + \alpha} (1 - \alpha^{-1}) = \frac{\beta(1-\alpha) + \alpha}{\beta(1-\alpha) + \alpha} \alpha^{-1}$$

Ex. 11 (i) $x_1 = \frac{\beta(1-\alpha) + \alpha}{\beta(1-\alpha) + \alpha}$ $x_2 = \frac{\beta(1-\alpha) + \alpha}{\beta(1-\alpha) + \alpha}$

$$T = \frac{\beta(1-\alpha) + \alpha}{\beta(1-\alpha) + \alpha} = \frac{\beta(1-\alpha) + \alpha}{\beta(1-\alpha) + \alpha}$$

$$x_1 = \frac{\beta(1-\alpha) + \alpha}{\beta(1-\alpha) + \alpha} \alpha^{-1} = \frac{\beta(1-\alpha) + \alpha}{\beta(1-\alpha) + \alpha} \alpha^{-1}$$

(ii) $x_1 = \frac{\beta(1-\alpha) + \alpha}{\beta(1-\alpha) + \alpha} \alpha^{-1}$

$$x_2 = \frac{\beta(1-\alpha) + \alpha}{\beta(1-\alpha) + \alpha} \alpha^{-1}$$

$$x_3 = \frac{\beta(1-\alpha) + \alpha}{\beta(1-\alpha) + \alpha} \alpha^{-1}$$

Ex. 12 (i) $x_1 = \frac{\beta(1-\alpha) + \alpha}{\beta(1-\alpha) + \alpha} \alpha^{-1}$

Solution: $W(x) = 0$ for $x = 0$.

Boundary conditions: $W(1) = 0$, $W(0) = 0$.

$$\text{--- } W(x) = \frac{\beta(1-\alpha) + \alpha}{\beta(1-\alpha) + \alpha}$$

$$W(x) = \frac{\beta(1-\alpha) + \alpha}{\beta(1-\alpha) + \alpha} \alpha^{-1}$$

$$W(x) = \frac{\beta(1-\alpha) + \alpha}{\beta(1-\alpha) + \alpha}$$

$$T = \frac{\beta(1-\alpha) + \alpha}{\beta(1-\alpha) + \alpha} \alpha^{-1} = \frac{\beta(1-\alpha) + \alpha}{\beta(1-\alpha) + \alpha} \alpha^{-1}$$

$$x_1 = \frac{\beta(1-\alpha) + \alpha}{\beta(1-\alpha) + \alpha} \alpha^{-1}$$

Ex-15 Assume a potential difference V_0 between the inner and outer spheres.

$$\int_{a}^{b} \vec{E} \cdot d\vec{s} = \int_a^b \frac{Q}{4\pi\epsilon_0 r^2} dr = V_0 \implies V = \frac{Q}{4\pi\epsilon_0} \left(\frac{1}{a} - \frac{1}{b} \right)$$

$$V_0 = -\int_a^b \vec{E} \cdot d\vec{s} = -k \int_a^b \frac{Q}{r^2} dr = k \left(\frac{Q}{a} - \frac{Q}{b} \right)$$

$$\implies k = \frac{V_0}{\frac{Q}{a} - \frac{Q}{b}} \quad \vec{E} = r \hat{e}_r = \frac{V_0}{a - \frac{a^2}{b}} \hat{e}_r$$

$$E = \int_a^b \vec{E} \cdot d\vec{s} = \int_a^b \frac{V_0}{a - \frac{a^2}{b}} dr = \frac{V_0 r}{a - \frac{a^2}{b}}$$

$$E = \frac{V_0}{a} = \frac{1}{4\pi\epsilon_0} \left(\frac{Q}{a} - \frac{Q}{b} \right) \text{ which matches original formula by Eq. 2.3.1 and 2.3.2}$$

Ex-16 Assume a current I between the spherical surfaces.

$$\vec{J} = \vec{e}_r \frac{I}{4\pi r^2} = r \hat{e}_r$$

$$\vec{E} = -\int_a^b \vec{E} \cdot d\vec{s} = -\int_a^b \frac{I}{4\pi r^2} dr = -\frac{I}{4\pi} \int_a^b \frac{dr}{r^2}$$

$$= -\frac{I}{4\pi} \int_a^b \frac{1}{r^2} \left(\frac{1}{a} - \frac{1}{b} \right) dr = -\frac{I}{4\pi} \ln \left(\frac{b}{a} \right)$$

$$E = \frac{I}{4\pi} = \frac{I}{4\pi r^2} \ln \left(\frac{b}{a} \right)$$

Ex-17 Assume $E_0 = \frac{V_0}{a} = \frac{Q}{4\pi\epsilon_0 a^2}$

$$E(r) = \int_a^b \vec{E} \cdot d\vec{s} = \int_a^b \frac{Q}{4\pi\epsilon_0 r^2} dr = \frac{Q}{4\pi\epsilon_0} \left(\frac{1}{a} - \frac{1}{b} \right)$$

$$E(r) = \int_a^b E_0 dr = E_0 \frac{r}{a} \left(\frac{1}{a} - \frac{1}{b} \right)$$

$$E = -\int_a^b E_0 dr = -\frac{E_0 r}{a} \left(\frac{1}{a} - \frac{1}{b} \right)$$

$$E = \frac{V_0}{a} = \frac{1}{4\pi\epsilon_0} \left(\frac{Q}{a} - \frac{Q}{b} \right)$$

Ex-18 $\vec{E} \cdot \vec{J} = 0 = \vec{E} \cdot (r \hat{e}_r) = r \vec{E} \cdot \hat{e}_r = (r \cdot) \cdot \vec{E} = 0$

$$E = \vec{e}_r E, \quad \vec{E} \cdot \vec{E} = \frac{1}{4\pi} \frac{I^2}{r^2} \left(\frac{1}{a} - \frac{1}{b} \right)^2 \implies E = \frac{I}{4\pi} \ln \left(\frac{b}{a} \right)$$

Substituting back: $R = \frac{d^2}{4} - a^2 \rightarrow R = \frac{d^2}{4} - \frac{a^2}{4}$
 $V = \int_0^R 2\pi r dr = \pi r^2 \Big|_0^R \rightarrow V = \frac{\pi d^2}{4} R - \frac{\pi a^2}{4} R$
 $E = \int_0^R E dr = \int_0^R \left(\frac{\rho}{2\epsilon_0} r \right) dr = \int_0^R \left(\frac{\rho}{2\epsilon_0} \right) \left[\frac{r^2}{2} \right] dr = \frac{\rho}{4\epsilon_0} \left[\frac{r^3}{3} \right]_0^R$
 $E = \frac{\rho}{4\epsilon_0} \left[\frac{R^3}{3} - \frac{a^3}{3} \right]$

Ex. 2.11 Assume charge $+q$ and $-q$ to concentrate at the centers of spheres 1 and 2 respectively. Find V_1 , V_2 .



$$V_1 = \frac{q}{4\pi\epsilon_0} \left(\frac{1}{a} - \frac{1}{d+b} \right)$$

$$V_2 = \frac{q}{4\pi\epsilon_0} \left(\frac{1}{d+a} - \frac{1}{b} \right)$$

$$C = \frac{q}{V_1 - V_2} = \frac{4\pi\epsilon_0}{\frac{1}{a} - \frac{1}{d+b} - \left(\frac{1}{d+a} - \frac{1}{b} \right)}$$

$$= 4\pi\epsilon_0 \frac{ab}{b - \frac{1}{d} - \frac{1}{a}}$$

$$E = \frac{1}{4\pi\epsilon_0} \left(\frac{1}{a} + \frac{1}{b} - \frac{1}{d+a} - \frac{1}{d+b} \right) = \frac{1}{4\pi\epsilon_0} \left(\frac{1}{a} + \frac{1}{b} - \frac{2}{d} \right)$$

Ex. 2.12



The curved line portion of the boundary of Fig. 2.12, if both the conductors and its charge are fixed with the same radius b exactly the same as that of Fig. 2.11. All boundary conditions are satisfied.

$$\Phi = \left(\frac{Q}{4\pi\epsilon_0} \right) \left(\frac{1}{a} - \frac{1}{b} \right)$$

where Φ and electrostatic potential V are simply related. The streamlines are similar to the E -lines of a parallel plate of the length, both carrying a charge q in the opposite way.

Soln According to problem 12-10, the current flow pattern would be the same as that of a whole sphere in an unbounded space condition. Hence the current flow would be radial. Assume a current I .

$$J = \epsilon_0 \frac{\partial E}{\partial t} \quad ; \quad E = \epsilon_0 \frac{\partial V}{\partial r}$$

$$\nabla \cdot J = -\int \text{div} = -\text{div} \int \frac{\partial V}{\partial r} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 J)$$

$$0 = \frac{1}{r^2} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 J) = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 I) \quad (1)$$

Soln Specified boundary conditions can be satisfied by both cases of Laplace's equation with zero separation constants: $\epsilon_2 = 0$ or $\epsilon_3 = 0$. (Take $\epsilon_2 = 0$, $\epsilon_3 = 0$, $\epsilon_1 = \epsilon_0 = 0$. $V(r) = A_0 r^2 + B_0$)

$$\Rightarrow \text{At } r = a, \quad V(a) = \frac{1}{2} = A_0 a^2 + B_0 \Rightarrow A_0 a^2 = \frac{1}{2} - B_0$$

$$\therefore V = \frac{1}{2} r^2 + B_0$$

$$\text{At } E = -\nabla V = -\epsilon_0 \frac{\partial V}{\partial r} \Rightarrow J = \text{div} \int \epsilon_0 \frac{\partial V}{\partial r}$$

Soln $V(r) = \frac{1}{2} (a_1 r^2 + a_2 r^{-2}) + a_3 \cos \theta + a_4 \sin \theta$

h.c.1: $V(a, \theta) = V(b, \theta) = a_3 \cos \theta + a_4 \sin \theta$

$$r = a, \quad V = \frac{1}{2} (a_1 a^2 + a_2 a^{-2}) + a_3 \cos \theta + a_4 \sin \theta$$

$$\text{When } V(r, \theta) = (a_1 r^2 + a_2 r^{-2}) \cos \theta, \quad a_3 = a_4 = 0 = \frac{1}{2} (a_1 a^2 + a_2 a^{-2})$$

h.c.2: $\frac{\partial V}{\partial r} \Big|_{r=a} = 0 \Rightarrow a_1 - \frac{a_2}{a^3} = 0, \quad a_3 = a^2 a_4 = -\frac{1}{2} a^2$

$$\therefore V(r, \theta) = -\frac{1}{2} (r - \frac{a^3}{r}) \cos \theta$$

$$J = -\text{div} \int \epsilon_0 \frac{\partial V}{\partial r} = \epsilon_0 \frac{\partial J}{\partial r}$$

$$= \epsilon_0 J \left(1 - \frac{a^3}{r^2}\right) \cos \theta - \epsilon_0 J_0 \left(1 + \frac{a^3}{r^2}\right) \sin \theta$$

$$= \epsilon_0 J_0 \cos \theta - \epsilon_0 J_0 \sin \theta \frac{a^3}{r^2} (\epsilon_1 \cos \theta + \epsilon_2 \sin \theta)$$

$$= \epsilon_0 J_0 = \frac{1}{2} \epsilon_0 (a_1 \cos \theta + a_2 \sin \theta), \quad r = a;$$

$$J = 0, \quad \text{radial}$$

Chapter 6

Static Magnetic Fields

Soln



$$\frac{\partial B_x}{\partial x} = \frac{\partial B_z}{\partial z} = -\mu_0 J_0 \delta(x) \delta(y) \quad \text{--- (1)}$$

$$\frac{\partial B_x}{\partial y} = -\frac{\partial B_z}{\partial x} = \mu_0 J_0 \delta(x) \delta(y) \quad \text{--- (2)}$$

$$B_y = B_z = 0$$

Combining (1) and (2)

$$\frac{\partial^2 B_x}{\partial x^2} = -\mu_0 J_0 \delta(x) \delta(y)$$

--- B_y and B_z are constant

At $x=0$, B_x and B_z are discontinuous

Substituting B_x in (1): $B_x = -\mu_0 J_0 x \delta(x) \delta(y)$ At $x=0$, B_x and B_z are discontinuous

∴ $B_x = \mu_0 J_0 x \delta(x) \delta(y)$ --- $y = \frac{\partial B_z}{\partial x} \delta(x) \delta(y)$ --- B_z is constant

$B_y = -\mu_0 J_0 x \delta(x) \delta(y)$ --- $B_z = \frac{\partial B_x}{\partial y} \delta(x) \delta(y)$ --- B_z and $B_y = -\frac{\partial B_x}{\partial x} \delta(x) \delta(y)$

From (1) and (2): $B^2 = B_x^2 + B_z^2 = \left(\frac{\partial B_x}{\partial x}\right)^2 = \mu_0^2 J_0^2 \delta(x) \delta(y)$

Soln $\frac{\partial B}{\partial x} = -\frac{\mu_0}{2} (J + \nabla \times J)$

∴ $B = \mu_0 J_x \hat{x} + \mu_0 J_y \hat{y}$

$\frac{\partial B}{\partial x} = 0$

$\frac{\partial B}{\partial y} = -\mu_0 J_x \hat{x}$ --- $\begin{cases} B_x = 0 \\ B_y = (J_x - \frac{\partial B_z}{\partial y}) \delta(x) \delta(y) = \frac{\mu_0}{2} J_x \end{cases}$

$\frac{\partial B}{\partial z} = -\mu_0 (J_y - \nabla \times J)_y$ --- $B_z = \left(\frac{\mu_0}{2} J_y - \mu_0 J_x\right) \delta(x) \delta(y)$ --- $B_z = \frac{\mu_0}{2} J_y$

If the direction is \hat{y} , B_z is constant and the only discontinuity is at $x=0$.

$B = \frac{\mu_0}{2} J_x \hat{x} + \frac{\mu_0}{2} J_y \hat{y}$ --- $B = \frac{\mu_0}{2} (J_x \hat{x} + J_y \hat{y})$ --- $B = \frac{\mu_0}{2} J$

Equation: $(\nabla \times B) = \mu_0 (J - \nabla \times J) = \mu_0 J$

Let $\frac{\mu_0}{2} J_x = B_x$, $\frac{\mu_0}{2} J_y = B_y$, $\frac{\mu_0}{2} J_z = B_z$

and $B = \frac{\mu_0}{2} J$ and $\nabla \times B = \mu_0 J$

$$c) \vec{E} = -\nabla \phi, \quad \vec{E} = -\frac{\partial \phi}{\partial x} \hat{i} - \frac{\partial \phi}{\partial y} \hat{j} - \frac{\partial \phi}{\partial z} \hat{k}$$

$$\left. \begin{aligned} \frac{\partial \phi}{\partial x} &= -\frac{\partial}{\partial x} \left(\frac{1}{4\pi\epsilon_0} \frac{q}{r} \right) = \frac{1}{4\pi\epsilon_0} \frac{qx}{r^3} \\ \frac{\partial \phi}{\partial y} &= -\frac{\partial}{\partial y} \left(\frac{1}{4\pi\epsilon_0} \frac{q}{r} \right) = \frac{1}{4\pi\epsilon_0} \frac{qy}{r^3} \\ \frac{\partial \phi}{\partial z} &= -\frac{\partial}{\partial z} \left(\frac{1}{4\pi\epsilon_0} \frac{q}{r} \right) = \frac{1}{4\pi\epsilon_0} \frac{qz}{r^3} \end{aligned} \right\} \begin{array}{l} \text{Component} \\ \text{method} \\ \text{method} \end{array} \left. \begin{array}{l} \text{Electric field vector} \\ \text{method} \\ \text{method} \end{array} \right\} \text{Electric field vector} \text{ method}$$

Ex-11 Application of Ampere's circuital law

$$\text{wire, } \vec{I} = I_0 \frac{\vec{r}}{r}$$

$$\text{wire, } \vec{I} = I_0 \frac{\vec{r}}{r}$$

$$\text{wire, } \vec{I} = I_0 \frac{\vec{r}}{r}$$

Ex-12



Using Ampere's law

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{enc}$$

$$\vec{B} = \frac{\mu_0 I_0}{4\pi r^2} \left(\frac{a}{r} \right)$$

$$\vec{B} = \frac{\mu_0 I_0}{4\pi r^2} \left(\frac{a}{r} \right)$$

$$\vec{B} = \frac{\mu_0 I_0}{4\pi r^2} \left(\frac{a}{r} \right)$$

$$\text{where } B_x = \frac{\mu_0 I_0}{4\pi r^2} \int_0^a \frac{a}{r^2} dx = \frac{\mu_0 I_0}{4\pi r^2} \ln \left(\frac{a}{r} \right)$$

$$B_y = \frac{\mu_0 I_0}{4\pi r^2} \int_0^a \frac{a}{r^2} dy = \frac{\mu_0 I_0}{4\pi r^2} \ln \left(\frac{a}{r} \right)$$

To find \vec{B} at $P(x, y, z)$, we add vectorially the contributions of the current along the wire and the wire part of point P using the result in part (a)

$$\vec{B}_P = \vec{B}_x + \vec{B}_y$$

$$\vec{B}_x = \frac{\mu_0 I_0}{4\pi r^2} \left[\ln \left(\frac{a}{r} \right) + \ln \left(\frac{a}{r} \right) \right]$$

$$\vec{B}_y = \frac{\mu_0 I_0}{4\pi r^2} \left[\ln \left(\frac{a}{r} \right) + \ln \left(\frac{a}{r} \right) \right]$$

$$\therefore \vec{B}_P = \frac{\mu_0 I_0}{4\pi r^2} \left[\ln \left(\frac{a}{r} \right) + \ln \left(\frac{a}{r} \right) + \ln \left(\frac{a}{r} \right) + \ln \left(\frac{a}{r} \right) \right]$$

Soln:



We find that \vec{B}_1 at O , due to wire, can be written as wire carrying a current I and making an angle α with the other end as shown.

$$\vec{B}_1 = \frac{\mu_0 I}{4\pi r} \sin \alpha \quad \text{Dir. into the page}$$

$$= \frac{\mu_0 I}{4\pi r} \left(\sin \alpha \right) \quad \text{Dir. into the page}$$

$$\vec{B}_2 = -I \frac{\mu_0}{2a} \hat{k} \quad \text{Dir. into the page}$$

$$\vec{B}_1 = -I \frac{\mu_0}{4\pi r} \sin \alpha \hat{k}$$

$$= -I \frac{\mu_0}{4\pi r} \sin \alpha \hat{k}$$

Applying the above result to the four sides of square of side a , we have

$$\vec{B}_1 = I \frac{\mu_0}{4\pi a} (\sin \alpha + \sin \alpha + \sin \alpha + \sin \alpha)$$

$$= \frac{I \mu_0}{\pi a} (\sin \alpha + \sin \alpha + \sin \alpha + \sin \alpha)$$

For this problem, $\alpha = 45^\circ$. So, the direction

$$\vec{B}_1 = \frac{I \mu_0}{\pi a} \sin 45^\circ \hat{k}$$

$$\vec{B}_2 = -I \frac{\mu_0}{2a} \hat{k}$$

Soln: The problem can be decomposed into two sub-problems for carrying a current of interest I .

1. A cylindrical tube carrying a uniformly distributed longitudinal surface current I and side a .

$$\vec{B}_1 = \begin{cases} 0, & \text{inside} \\ \frac{\mu_0 I}{2a} \hat{k}, & \text{out} \end{cases}$$

2. A solenoid with a turns per unit length carrying a current I and a .

$$\vec{B}_2 = \begin{cases} \mu_0 I n \hat{k}, & \text{inside} \\ 0, & \text{out} \end{cases}$$

$$\text{Total } \vec{B} = \vec{B}_1 + \vec{B}_2$$

Ex. 1 From Example 4-6, Eq. (10):



Direction of \vec{B} is determined by the right-hand rule.

$$dB = \frac{\mu_0 I dy}{2\pi r^2} \left(\frac{r}{2}\right) d\theta$$

$$B = \frac{\mu_0 I}{2\pi} \int_{-h/2}^{h/2} \frac{dy}{(b^2 + y^2)^{3/2}}$$

$$= \frac{\mu_0 I}{2\pi} \left[\frac{y}{b^2 \sqrt{b^2 + y^2}} + \frac{1}{b^2 \tan^{-1} \frac{y}{b}} \right]$$

$$\rightarrow \mu_0 \left(\frac{I}{2}\right) \left[\frac{1}{b} \right] \text{ at } y = \pm \frac{h}{2}$$

$$B = \mu_0 \frac{I}{2b}$$

At $\theta = 0$, the magnetic flux density due to an infinitely long strip of width dy is

$$dB = \frac{\mu_0 I dy}{2\pi r^2} \left(\frac{r}{2} \right) d\theta$$

$$r = \sqrt{b^2 + y^2}$$

$$\therefore B = \int dB = B_x \hat{i}_x + B_y \hat{j}_y$$

where

$$B_x = -\frac{\mu_0 I}{2\pi} \int_{-h/2}^{h/2} \frac{y dy}{(b^2 + y^2)^{3/2}}$$

$$= \frac{\mu_0 I}{2\pi} \left[\frac{1}{\sqrt{b^2 + y^2}} - \frac{1}{\sqrt{b^2}} \right]$$

$$B_y = \frac{\mu_0 I}{2\pi} \int_{-h/2}^{h/2} \frac{b dy}{(b^2 + y^2)^{3/2}}$$

$$= \frac{\mu_0 I}{2\pi} \frac{1}{b} \left[\frac{y}{\sqrt{b^2 + y^2}} + \frac{1}{\sqrt{b^2}} \right]$$



Top view

Ex. 2 This problem is a superposition of two problems:

$$B = B_1 + B_2$$

where

B_1 is the magnetic flux density of I due to the

Simultaneously wires carrying equal and opposite currents
 Attractive B_2 points out of paper:

$$B_2 = \mu_0 \frac{I_2}{2\pi r_2}$$

2. B_2 is the magnetic flux density at P due to a half wire. Taking one half of the wire as length $2a$:

$$B_2 = \mu_0 \frac{I_2}{4a}$$

$$\therefore B = \mu_0 \frac{I_2}{4a} \left(\frac{1}{r_1} + \frac{1}{r_2} \right)$$

Ex 10 Use Eq (9-28) $B = \frac{\mu_0 I_1 I_2}{4\pi} \left[\frac{1}{(a^2 + z^2)^{3/2}} - \frac{1}{(a^2 + (z+2a)^2)^{3/2}} \right]$



$$\text{At } z=0, B = \frac{\mu_0 I_1 I_2}{4\pi} \left[\frac{1}{(a^2 + 0)^{3/2}} - \frac{1}{(a^2 + (0+2a)^2)^{3/2}} \right]$$

$$\text{As } \frac{dB}{dz} = \frac{d}{dz} \left[\frac{1}{(a^2 + z^2)^{3/2}} - \frac{1}{(a^2 + (z+2a)^2)^{3/2}} \right]$$

$$= \frac{3z(a^2 + z^2)^{-5/2}}{1} - \frac{3(z+2a)(a^2 + (z+2a)^2)^{-5/2}}{1}$$

At the midpoint, $z = a$, $\frac{dB}{dz} = 0$

$$\text{As } \frac{dB}{dz} = -\frac{3\mu_0 I_1 I_2}{4\pi} \left[\frac{1}{(a^2 + z^2)^{5/2}} - \frac{1}{(a^2 + (z+2a)^2)^{5/2}} \right]$$

$$\text{At } z=0, \frac{dB}{dz} = -\frac{3\mu_0 I_1 I_2}{4\pi} \left[\frac{1}{(a^2 + 0)^{5/2}} - \frac{1}{(a^2 + (0+2a)^2)^{5/2}} \right] \text{ and it is not}$$

Ex 11 Use Eq (9-28) for a wire of length $2a$.

$$B = \mu_0 \frac{I_1 I_2}{4\pi} \left[\frac{1}{(a^2 + z^2)^{3/2}} - \frac{1}{(a^2 + (z+2a)^2)^{3/2}} \right]$$



In this problem, $a = \frac{z}{\sqrt{2}}$, $z = \frac{2a}{\sqrt{2}}$

$$B = \mu_0 \left(\frac{I_1 I_2}{4\pi} \right) = \mu_0 \frac{I_1 I_2}{4\pi} \text{ at } \frac{z}{\sqrt{2}}$$

When a is very large, $\frac{z}{\sqrt{2}} \approx \frac{z}{2}$, $B \rightarrow \mu_0 \frac{I_1 I_2}{4\pi}$, which is the same as Eq (9-28) with $a = z$.

Ex-12 $B_0 = \frac{\mu_0 I}{2a}$; $B = \int B_0 dr = \frac{\mu_0 I}{2a} \int_0^a r dr = \frac{\mu_0 I}{4a} a^2 = \frac{\mu_0 I a}{4}$

If B_0 at $r = \frac{a}{2}$ is used, $B = \frac{\mu_0 I a}{4} \left(\frac{a}{2} \right)$

% error = $\frac{\frac{\mu_0 I a}{4} - \frac{\mu_0 I a}{8}}{\frac{\mu_0 I a}{4}} \times 100 = \left[\frac{\frac{\mu_0 I a}{4} - \frac{\mu_0 I a}{8}}{\frac{\mu_0 I a}{4}} \right] \times 100 = 25\%$

Ex-13 $B = B_1$; $\oint B \cdot dl = \mu_0 I$



If there is a hole,

$$\mu_0 I_{enc} = \mu_0 I'$$

$$\rightarrow B_1 = \frac{\mu_0 I'}{2\pi r} \text{ from } \begin{cases} B_1 = \frac{\mu_0 I'}{2\pi r} \\ B_2 = \frac{\mu_0 I'}{2\pi r} \end{cases}$$

For $-I'$ in the hole portion,

$$B_2 = \frac{\mu_0 I'}{2\pi r} \text{ from } \begin{cases} B_2 = \frac{\mu_0 I'}{2\pi r} \\ B_3 = \frac{\mu_0 I'}{2\pi r} \end{cases}$$

Superposing B_1 and B_2 and noting that I_1 and I_2 are in

the same direction, we have $B_0 = B_1 + B_2 = 0$, and $B_1 = B_2 = B_3 = \frac{\mu_0 I'}{2\pi r}$

Ex-14 $B = \frac{\mu_0 I}{2a} r \rightarrow B = \frac{\mu_0 I}{2a} \left(\frac{a}{2} - \frac{a}{2} \right) = \frac{\mu_0 I}{2a} \frac{a}{2}$

For $r < \frac{a}{2}$, $B_1 = \frac{\mu_0 I}{2a} r$ gives $B = \frac{\mu_0 I}{2a} \left(\frac{a}{2} - r \right)$

For $r > \frac{a}{2}$, $B_2 = \frac{\mu_0 I}{2a} r$ gives $B = \frac{\mu_0 I}{2a} \left(\frac{a}{2} + r \right)$

Integrating, $B_1 = \frac{\mu_0 I}{2a} \left[\frac{a}{2} \left(\frac{a}{2} - r \right) + c_1 \right]$, $0 \leq r \leq \frac{a}{2}$

$$B_2 = \frac{\mu_0 I}{2a} \left[\frac{a}{2} \left(\frac{a}{2} + r \right) + c_2 \right]$$
, $r \geq \frac{a}{2}$

At $r = \frac{a}{2}$, $B_1 = B_2 \rightarrow c_1 = \frac{\mu_0 I}{2a} \left(\frac{a}{2} - \frac{a}{2} \right) + c_2$

$$\therefore B_1 = B_2 = \frac{\mu_0 I}{2a} \left[\frac{a}{2} \left(\frac{a}{2} + r \right) + c_2 \right]$$
, $r \geq \frac{a}{2}$

Ex-15 $B_0 = \frac{\mu_0 I}{2a}$ for one wire; $B = \frac{\mu_0 I}{2a} \left(\frac{a}{2} - \frac{a}{2} \right) = 0$

For two wires carrying equal and opposite currents,

a) $B = \frac{\mu_0 I}{2a} \left[\frac{\mu_0 I}{2a} \left(\frac{a}{2} - \frac{a}{2} \right) + \frac{\mu_0 I}{2a} \left(\frac{a}{2} + \frac{a}{2} \right) \right] = \frac{\mu_0 I}{2a} \left[\frac{\mu_0 I}{2a} \left(\frac{a}{2} + \frac{a}{2} \right) \right]$

bl For a very long horizontal transmission line, assume

$$R = R_0 \frac{dl}{l} \quad \Delta V = R_0 \frac{dl}{l} \int_0^l \frac{dV}{dl} dx$$

cl $R = R_0 \frac{dl}{l} = R_0 \frac{dV}{V}$

$$= R_0 \frac{dV}{V} \left[\frac{1}{1 - \frac{R_0}{V}} - \frac{1}{1 - \frac{R_0}{V_0}} \right] = R_0 \left[\frac{V_0}{V_0 - R_0} - \frac{V}{V - R_0} \right]$$

$$= R_0 \left[\frac{V_0}{V_0 - R_0} - \frac{V}{V - R_0} \right]$$

al To find the equation for magnetic flux (lines)

$$\frac{d\Phi}{dt} = \frac{dV}{dt} \implies \frac{d\Phi}{dt} = \frac{dV}{dt} \implies \frac{d\Phi}{dt} = \frac{dV}{dt}$$

$\implies d\Phi = dV \implies \Phi = V + \text{constant}$

Thus, $\frac{d\Phi}{dt} = \frac{dV}{dt} = \frac{dV}{dt} = \frac{dV}{dt}$

Ex 11.1 Apply divergence theorem to $(\nabla \cdot \mathbf{E})$, where \mathbf{E} is a constant vector.

$$\int_V \nabla \cdot \mathbf{E} \, dV = \oint_S \mathbf{E} \cdot d\mathbf{S} \quad \text{--- (1)}$$

Now, from problem 11.1: $\nabla \cdot \mathbf{E} = \frac{\rho}{\epsilon_0}$

from Eq. 11.1: $\oint_S \mathbf{E} \cdot d\mathbf{S} = \frac{1}{\epsilon_0} \int_V \rho \, dV$

Substituting (1) and (2) in (1)

$$\int_V \left(\frac{\rho}{\epsilon_0} \right) dV = \frac{1}{\epsilon_0} \int_V \rho \, dV \implies \int_V \rho \, dV = \int_V \rho \, dV$$

Ex 11.2



a) Given $\mathbf{E} = E_0 \hat{x}$

$$E_x = E_0 \implies \oint_S \mathbf{E} \cdot d\mathbf{S} = E_0 \int_S dS = E_0 \cdot ab$$

b) Given $\mathbf{E} = E_0 \hat{y}$

$$E_y = E_0 \implies \oint_S \mathbf{E} \cdot d\mathbf{S} = E_0 \int_S dS = E_0 \cdot bc$$

Ex 11.3 a) Given

$$\mathbf{E} = E_0 \hat{x} \implies \oint_S \mathbf{E} \cdot d\mathbf{S} = E_0 \int_S dS = E_0 \cdot ab$$

b) $\mathbf{E} = E_0 \hat{y} \implies \oint_S \mathbf{E} \cdot d\mathbf{S} = E_0 \int_S dS = E_0 \cdot bc$

Ex 11.1



a) $E = \rho \int dV E = -\rho \int_V \frac{\partial \phi}{\partial z} dz = -\rho \int_0^h \frac{\partial \phi}{\partial z} dz = -\rho \phi|_0^h = -\rho \phi(h) = -\rho \frac{1}{2} \omega^2 R^2 h$ which is the same as Eq. 11-111.

Ex 11.2 A cylindrical bar magnet having a uniform magnetization M along the z -axis is equivalent to a \vec{J}_m on the flat ends as $\vec{J}_m = \nabla \times \vec{M} = \nabla_{\phi} M \hat{\phi} = M \hat{\phi}$ on the cylinder with \vec{M} at its base point. It also has the \vec{J}_m flowing on a cylindrical shell of length h and radius R in the same direction as a circular loop of radius R carrying a current I (Eq. 11-112), which is the same as Eq. 11-111 obtained in Example 1-7 where the total dipole moment of the cylindrical magnet is $M \pi R^2 h$ (Eq. 11-110).

Ex 11.3



a) $\vec{J}_m = \nabla \times \vec{M} = 0$
 $\vec{J}_m = \nabla_{\phi} M = \nabla_{\phi} M \hat{\phi} = M \hat{\phi}$
 $= M \hat{\phi} \text{ on } z$

b) Apply Eq. 11-111 to a loop of radius R that carries a current I (Eq. 11-112):
 $d\vec{L} = I \hat{\phi} \frac{R d\phi}{\sin \theta} = I \hat{\phi} \frac{R d\phi}{R}$
 $= I \hat{\phi} d\phi \text{ on } z$

$$\vec{E} = \int d\vec{E} = -\int \frac{d\vec{L} \times \hat{r}}{r^2} \text{ on } z = -\int \frac{I \hat{\phi} \times \hat{r}}{R^2} = \int \frac{I \hat{z}}{R^2} d\phi$$

Ex. 12 a) $V_1 = \frac{1}{\mu_0} \frac{d\Phi_1}{dt} = \frac{1}{\mu_0} \frac{d(\mu_0 n_1 I_1)}{dt} = \mu_0 n_1 \dot{I}_1 = \mu_0^2 (n_1^2) \dot{I}_1$
 $V_2 = \frac{1}{\mu_0} \frac{d\Phi_2}{dt} = \frac{1}{\mu_0} \frac{d(\mu_0 n_2 I_2)}{dt} = \mu_0 n_2 \dot{I}_2 = \mu_0^2 (n_2^2) \dot{I}_2$

b) $V_1 = \mu_0 n_1 \dot{I}_1 = \mu_0^2 n_1^2 \dot{I}_1 = \mu_0^2 n_1^2 \dot{I}_1$
 $V_2 = \mu_0 n_2 \dot{I}_2 = \mu_0^2 n_2^2 \dot{I}_2 = \mu_0^2 n_2^2 \dot{I}_2$
 $V_1 = \frac{1}{\mu_0} \frac{d\Phi_1}{dt}, V_2 = \mu_0 n_2 \frac{d\Phi_2}{dt} = \mu_0^2 n_2^2 \dot{I}_2$

c) $V_1 = \mu_0 n_1 \dot{I}_1, V_2 = \mu_0 n_2 \dot{I}_2 = \mu_0^2 n_2^2 \dot{I}_2 = \mu_0^2 n_2^2 \dot{I}_2$

Ex. 13 Magnetic circuit:



$\frac{1}{\mu_0} \frac{d\Phi}{dt} = \frac{1}{\mu_0} \frac{d(\mu_0 n I)}{dt} = n \dot{I}$

Magnetizing force:

Flux and current through circuit are always equal: $I = I$

$V_1 = \frac{d\Phi_1}{dt} = \frac{d(\mu_0 n I)}{dt} = \mu_0 n^2 \dot{I}$

$V_2 = \frac{d\Phi_2}{dt} = \mu_0 n^2 \dot{I} = \mu_0^2 n^2 \dot{I}$

a) $V_1 = \frac{d\Phi_1}{dt} = \mu_0 n^2 \dot{I}, V_2 = \frac{d\Phi_2}{dt} = \mu_0^2 n^2 \dot{I}$

b) $V_1 = \frac{d\Phi_1}{dt} = \mu_0 n^2 \dot{I}$

$V_2 = \frac{1}{\mu_0} \frac{d\Phi_2}{dt} = \mu_0 n^2 \dot{I}$ in air gap

$V_3 = \frac{1}{\mu_0} \frac{d\Phi_3}{dt} = \mu_0 n^2 \dot{I}$

Ex. 14 a) $V_1 = \frac{d\Phi_1}{dt}$ per unit length in direction of I

$V_2 = \frac{d\Phi_2}{dt}$

Which per unit volume in air: $V_1 = \mu_0 n^2 \dot{I}$

Then: $V_2 = \mu_0^2 n^2 \dot{I}$

Ex. 15 $V_1 = \mu_0 n^2 \dot{I}, V_2 = \mu_0^2 n^2 \dot{I}$

$V_1 = \mu_0 n^2 \dot{I}, V_2 = \mu_0^2 n^2 \dot{I}$

$V_3 = \mu_0^2 n^2 \dot{I}$

$V_4 = \mu_0^2 n^2 \dot{I}$
 (Magnetic circuit element)

Ex 11



$$a) \vec{r}_1 = \vec{r}_2 \cos \alpha = \vec{r}_2 \cos(\beta + \gamma)$$

$$\vec{r}_1 = \vec{r}_2 \cos \alpha = \vec{r}_2 \cos(\beta + \gamma)$$

$$\vec{r}_2 = \frac{\vec{r}_1}{\cos(\beta + \gamma)} = \vec{r}_1 \sec(\beta + \gamma)$$

$$\rightarrow \vec{r}_2 = \vec{r}_1 \sec(\beta + \gamma)$$

$$\vec{r}_2 = \vec{r}_1 \sec(\beta + \gamma)$$

$$\therefore \vec{r}_2 = \vec{r}_1 \sec(\beta + \gamma) = \vec{r}_1 \sec(\beta + \gamma)$$

$$\cos \alpha = \frac{\vec{r}_1}{\vec{r}_2} \cos \alpha = \cos(\beta + \gamma) = \cos \beta \cos \gamma - \sin \beta \sin \gamma \quad \text{Q.E.D.}$$

b) If $\vec{r}_1 = \vec{r}_2 \cos \alpha + \vec{r}_3 \sin \alpha$, $\vec{r}_1 = \vec{r}_2 \cos \alpha + \vec{r}_3 \sin \alpha$

$$\vec{r}_2 = \frac{\vec{r}_1}{\cos \alpha} = \vec{r}_1 \sec \alpha \rightarrow \vec{r}_2 = \frac{1}{\cos \alpha} \vec{r}_1 = \sec \alpha \vec{r}_1$$

$$\vec{r}_3 = \vec{r}_1 \tan \alpha \quad \therefore \vec{r}_3 = \vec{r}_1 \tan \alpha = \vec{r}_1 \tan \alpha$$

$$\vec{r}_3 = \vec{r}_1 \tan \alpha = \vec{r}_1 \tan \alpha = \vec{r}_1 \tan \alpha = \vec{r}_1 \tan \alpha$$

Ex 12) a) Consider two situations (I) and (II) both in air and (III) in water. Both in magnetic medium with relative permeability μ .



Find \vec{r}_1 and \vec{r}_2 at P (air)

$$\vec{r}_1 = \frac{\vec{r}}{\cos \alpha} = \vec{r} \sec \alpha$$

$$\vec{r}_2 = \frac{\vec{r}}{\sin \alpha} = \vec{r} \csc \alpha$$

$$\vec{r}_3 = \vec{r} \tan \alpha$$

$\therefore \vec{r}_1 = \vec{r}_2 \cos \alpha$ and $\vec{r}_3 = \vec{r}_1 \tan \alpha$ (Boundary conditions satisfied)

Now \vec{r}_1 and \vec{r}_2 at P (water)

$$\vec{r}_1 = \frac{\vec{r}}{\mu \cos \alpha} = \frac{\vec{r}}{\mu} \sec \alpha$$

$$\vec{r}_2 = \frac{\vec{r}}{\mu \sin \alpha} = \frac{\vec{r}}{\mu} \csc \alpha$$

$$\vec{r}_3 = \vec{r} \tan \alpha$$

b) For $\mu = 1$, $\vec{r}_1 = \frac{\vec{r}}{\cos \alpha} = \vec{r} \sec \alpha$

Refer to the following figure.



$$E_1 = \frac{xy}{r^3} (-x, y, 0),$$

$$E_2 = \frac{xy}{r^3} (-x, -y, 0),$$

$$\therefore E = E_1 + E_2$$

$$= -\frac{xy}{r^3} \left[\frac{y^2 + z^2}{r^2} + \frac{xy}{r^2} \right] \hat{i} + \frac{xy}{r^3} \left[\frac{x^2 + z^2}{r^2} + \frac{xy}{r^2} \right] \hat{j}$$

Ex-14



$$\text{a) If } z=0, \quad E_1 = E_2 = 0,$$

$$E_1 \text{ continuous across } z=0,$$

$$E_2 \text{ is } \hat{i} \text{ or } -\hat{i} \text{ across } z=0$$

$$\text{Average } E_2 = 0 \text{ (Average out of } \hat{i} \text{ and } -\hat{i} \text{)}$$

$$\text{b) If } z \neq 0, \quad E_1 = 0, \text{ but } E_2 \text{ is finite.}$$

At surface current, $E_1 = E_2 = 0$

E_1 continuous across $z=0$.

Average E_2 is 0 (Average into the paper)

$$\text{d) } E_2 = E_1 + (E_2)_z, \text{ where } E_1 = \frac{xy}{r^3} \left[\frac{y^2 + z^2}{r^2} + \frac{xy}{r^2} \right] \hat{i} + \frac{xy}{r^3} \left[\frac{x^2 + z^2}{r^2} + \frac{xy}{r^2} \right] \hat{j}$$

$$\text{e) } E_2 = E_1 - (E_2)_z = E_1 - (E_2)_z$$

$$\text{f) } E_2 = -E_2 \text{ (Average out of } \hat{i} \text{ and } -\hat{i} \text{)}$$

$$\text{g) } E_2 = 0$$

Ex-15



$$E = E_1 + E_2 = E_1 \frac{2R}{r} \hat{r}, \quad r = \sqrt{R^2 + z^2}$$

$$E = \frac{2R}{r} \left[\frac{R^2}{r^2} \frac{R}{r} \hat{r} + \frac{Rz}{r^2} \hat{z} \right] = \frac{2R^2}{r^3} (R \hat{r} + z \hat{z})$$

$$\therefore E = \frac{2R^2}{r^3} (R \hat{r} + z \hat{z}) = \frac{2R^2}{r^3} (R \hat{r} + z \hat{z})$$

$$\text{At } z=0, \quad E_2 \text{ is } \frac{2R^2}{r^3} (R \hat{r} + z \hat{z})$$

$$E = E_1 + E_2 = \frac{2R^2}{r^3} (R \hat{r} + z \hat{z}) + \frac{2R^2}{r^3} (R \hat{r} + z \hat{z})$$

Ex. 22. For parallel, $E_1 = \frac{1}{2} E_2 = \frac{1}{2} \frac{\mu_0 I}{2\pi r} \left[1 - \frac{r^2}{(2a)^2} \right]$
 $= \frac{1}{4} \frac{\mu_0 I}{\pi r} \left[\frac{2a^2 - r^2}{2a^2} \right]$.

Magnetic energy per unit length stored in the tube is

$$W'_L = \frac{1}{2} \int_{a_1}^{a_2} B_1^2 \pi r dr$$

$$= \frac{\mu_0^2 I^2}{8\pi} \left\{ \frac{(2a^2 - r^2)^2}{4a^4} \pi r \Big|_a^{2a} + \frac{d}{4\pi} \frac{dW'_L}{dr} \right\}$$

From Eqs. (2-197), (2-198) and (2-194) we have

$$L = \frac{1}{I^2} (W'_L + W'_L + W'_L)$$

$$= \frac{\mu_0}{4\pi} \left[\frac{1}{2} + \frac{1}{2} + \frac{d}{4\pi} \frac{dW'_L}{dr} \right] \pi$$

Ex. 23



At a distance r from an infinitely long wire carrying a current $I = I_0 \frac{z}{\sqrt{z^2 + a^2}}$

For a unit length the flux due to I is less than that due to the current alone by a factor

$$E_1 = \frac{\mu_0 I}{2\pi r} \frac{z}{\sqrt{z^2 + a^2}} = \frac{\mu_0 I_0 z}{2\pi r \sqrt{z^2 + a^2}}$$

That due to I in the wire is

$$E_2 = \frac{\mu_0 I_0}{2\pi} \frac{z}{\sqrt{z^2 + a^2}}$$

Total flux linkage per unit length

$$L'_L = E_1 - E_2 = \frac{\mu_0 I_0}{2\pi} \ln \frac{\sqrt{z^2 + a^2}}{z}$$

$$= \frac{\mu_0 I_0}{2\pi} \left[\frac{\sqrt{z^2 + a^2}}{z} - \frac{z}{z} \right] = \frac{\mu_0 I_0}{2\pi} \left[\frac{\sqrt{z^2 + a^2}}{z} - 1 \right]$$

$$\therefore W'_L = \frac{\mu_0 I_0^2}{4\pi} \ln \left(1 + \frac{a^2}{z^2} \right)$$

Ex. 24 For I in the long straight wire, E_1 by $\frac{\mu_0 I}{2\pi r}$

$$L'_L = \int E_1 dr - \int E_2 \frac{r}{a} dr = \frac{\mu_0 I}{2\pi} \left[\ln \frac{b}{a} \right] \pi$$

$$= \frac{\mu_0 I^2}{4\pi} \left[\ln \frac{b}{a} + \frac{1}{2} \right] = \frac{\mu_0 I^2}{4\pi} \left[\frac{1}{2} + \ln \frac{b}{a} \right]$$

Ex:42



Assume a current I .

$$B \text{ at } P \text{ due to } I = \frac{\mu_0 I I_0}{4\pi R^2 \sqrt{a^2 + z^2}}$$

$$A_{\perp} = \frac{\mu_0 I}{4\pi} \int_{-\pi/2}^{\pi/2} \frac{\sin \theta d\theta}{a^2 + z^2}$$

$$= \frac{\mu_0 I}{4\pi} \int_{-\pi/2}^{\pi/2} \frac{\sin \theta d\theta}{a^2 + z^2} = \frac{\mu_0 I}{4\pi} \left[-\cos \theta \right]_{-\pi/2}^{\pi/2}$$

$$A_{\perp} = \frac{\mu_0 I}{2\pi} \sin \theta \Big|_{-\pi/2}^{\pi/2}$$

Ex:43 Approximate the magnetic flux due to the long loop taking with the small loop by that due to two infinitely long wires carrying equal and opposite current I .

$$A_{\perp} = \frac{\mu_0 I a}{2\pi} \int \left(\frac{1}{a+x} - \frac{1}{a-x} \right) dx = \frac{\mu_0 I a}{2\pi} \ln \left(\frac{a+x}{a-x} \right)$$

$$A_{\perp} = \frac{\mu_0 I a}{\pi} = \frac{\mu_0 I a}{2\pi} \ln \left(\frac{a+x}{a-x} \right)$$

Ex:44 $\vec{B} = (a - bx) \hat{i} + (c + dx) \hat{j} + (e + fx) \hat{k}$

$$\Rightarrow \nabla \cdot \vec{B} = \frac{\partial}{\partial x} (a - bx) + \frac{\partial}{\partial y} (c + dx) + \frac{\partial}{\partial z} (e + fx) = -b + d + f$$

$$\frac{\partial \psi}{\partial x} = \frac{\partial}{\partial x} (ax + by + cz) = 0, \quad \frac{\partial \psi}{\partial y} = \frac{\partial}{\partial y} (ax + by + cz) = 0$$

$$\therefore a = \frac{b}{2} = -\frac{d}{2} \text{ for minimum } \psi$$

$$B) \nabla \times \vec{B} = \frac{\partial}{\partial x} (-dx - fx) \hat{k} \rightarrow -d \hat{k} / \sqrt{2}$$

Ex:45



$$B_1 = B_2 = B_3 = \frac{\mu_0 I}{2\pi r}, \quad r = \frac{a}{\sqrt{3}}$$

$$B_1 = B_2 = B_3 = \frac{\mu_0 I \sqrt{3}}{2\pi a}$$

Force per unit length on wire 1

$$F_1 = -\frac{\mu_0 I_1 I_2}{2\pi r} = -\frac{\mu_0 I^2 \sqrt{3}}{2\pi a}$$

$$\rightarrow -\frac{\mu_0 I^2 \sqrt{3}}{2\pi a} = -\frac{\mu_0 I^2 \sqrt{3}}{2\pi a} \text{ (out)}$$

Force on all three wires are of equal magnitude and towards the center of the triangle.

Ex 11 Magnetic field intensity at the wire due to the current of $I = \frac{1}{2} \text{ amp}$ in an elemental dip is



$$dH = \frac{\mu_0 I}{4\pi r^2} = \frac{\mu_0 I dl \cos \theta}{4\pi r^2}$$

Symmetry \rightarrow H at the wire has only y -component.

$$H = \mu_0 I \int \cos \theta \left(\frac{1}{r^2} \right) = \mu_0 I \int \frac{\cos \theta dl}{r^2} \\ = \mu_0 I \int \frac{\cos^3 \theta}{r^2} dl$$

$$F = F \sin \theta = (-\mu_0 I) \left[\mu_0 I \int \frac{\cos^3 \theta}{r^2} dl \right] \sin \theta \quad (1)$$

Ex 12 From Problem 11-11 we have the y -component of the magnetic flux density at an arbitrary point $P(x, z)$ in the right-hand wire due to I_1 in the left-hand wire

$$B_{y1} = -\frac{\mu_0 I_1}{4\pi r^2} \left[\cos^{-1} \left(\frac{z}{r} \right) + \cos^{-1} \left(\frac{z+z'}{r} \right) \right]$$

The x -component of the force on a strip of width dy due to I_2 in the right-hand conductor is

$dF_x = \left(\frac{\mu_0 I_2}{4\pi r^2} \right) dy$ (in the + x direction, a repulsive force)

$$F_x = \mu_0 I_2 \int dF_x = \mu_0 I_2 \frac{\mu_0 I_1}{4\pi} \int \left[\cos^{-1} \left(\frac{z}{r} \right) + \cos^{-1} \left(\frac{z+z'}{r} \right) \right] dy \\ = \mu_0 I_1 I_2 \left[1 + \cos^{-1} \left(\frac{z}{r} \right) - \cos^{-1} \left(\frac{z+z'}{r} \right) \right] \text{ per unit length}$$

There is equal force in the y -direction.

Ex 13 H due to I_1 in the straight wire in the x -direction at an elemental area dA in the circular loop is

$$dH = \mu_0 \frac{I_1 dA}{4\pi r^2 \cos^2 \theta}$$



F has no net y -component

$$F_x = -\mu_0 I_2 \int \left(\mu_0 I_1 dA \right) \cos \theta \\ = -\mu_0 I_1 I_2 \int \frac{dA \cos \theta}{4\pi r^2 \cos^2 \theta} \\ = -\mu_0 I_1 I_2 \left[\frac{2\pi a^2}{4\pi a^2} - 1 \right] \text{ (repulsive force)}$$

Ex. 22 $\vec{E} = \epsilon_0 \frac{\partial \vec{E}}{\partial t} \left(\frac{1}{r} + \frac{1}{r^2} \right)$ $d\vec{l} = \hat{y} dy$



(A rectangular problem.)

$$\begin{aligned} d\vec{E} &= \epsilon_0 \frac{\partial \vec{E}}{\partial t} \left(\frac{1}{r} + \frac{1}{r^2} \right) dy \\ \vec{E} &= \epsilon_0 \frac{\partial \vec{E}}{\partial t} \int \left(\frac{1}{r} + \frac{1}{r^2} \right) dy \\ &= \epsilon_0 \frac{\partial \vec{E}}{\partial t} \ln \left(\frac{r}{r_0} \right) \end{aligned}$$

Ex. 23



Divide the slab into $2L/3$ $L/3$ $L/3$

(\vec{E}_1 due to \vec{E}_2 and \vec{E}_3 due to \vec{E}_1)

Sum \vec{E}_1 and \vec{E}_2 and \vec{E}_3 to

obtain \vec{E}

$$\vec{E} = \vec{E}_1 + \vec{E}_2 + \vec{E}_3 = \vec{E}$$

$$= \epsilon_0 \frac{\partial \vec{E}}{\partial t} \left(\frac{1}{r_1} + \frac{1}{r_2} + \frac{1}{r_3} \right)$$

Ex. 24 Let $\vec{E} = \epsilon_0 \frac{\partial \vec{E}}{\partial t}$ be the electric field of the circular slab.

The magnetic energy stored in a section of length L is

$$W_M = \frac{1}{2} \epsilon_0 L^2$$

$$L = \frac{1}{2} = \frac{1}{2} \int_0^L \epsilon_0 \frac{\partial \vec{E}}{\partial t} dt = \frac{1}{2} \int_0^L \frac{\partial \vec{E}}{\partial t} dt = \frac{1}{2} \epsilon_0 \frac{\partial \vec{E}}{\partial t} L$$

$$\vec{E} = \epsilon_0 \frac{\partial \vec{E}}{\partial t} = \epsilon_0 \left(\frac{\partial \vec{E}}{\partial t} \right) L = \epsilon_0 \frac{\partial \vec{E}}{\partial t} L$$

Ex. 25 Divide the circular loop into many small loops, each with a magnetic dipole moment $\vec{m} = \epsilon_0 \frac{\partial \vec{E}}{\partial t}$ of width δ .

$$\vec{E} = \int \vec{E} = \epsilon_0 \int \frac{\partial \vec{E}}{\partial t} \delta = \epsilon_0 \frac{\partial \vec{E}}{\partial t} \delta \int \delta = \epsilon_0 \frac{\partial \vec{E}}{\partial t} \delta \int \delta = \epsilon_0 \frac{\partial \vec{E}}{\partial t} \delta \int \delta$$

— This torque is in the direction of aligning the dipoles produced by \vec{E} in the loop with that of \vec{E} due to \vec{E} in the straight wire.

Ex. 11. \vec{E} at the end of the large circular face of wire carrying a current I_0 is \vec{E}_1 (setting $\vec{E}_2 = 0$)

$$\vec{E}_1 = E_1 \frac{\vec{r}_1}{r_1}$$

Force on the small circular wire: $F = \int \vec{E}_1 \cdot d\vec{q} = \int (E_1 \cos \theta) dq = E_1 \int \cos \theta dq$
 (multiplying under $\frac{dq}{d\theta} = \frac{2\pi R_2 \sin \theta}{2\pi} = R_2 \sin \theta$ since \vec{E}_1 is a direction to align the magnetic flux produced by I_1 & I_0)

Ex. 12



$$\vec{E}_1 \text{ (uniform field region inside)}$$

$$= \frac{E_1}{r_1^2} (R_2 \cos \theta + R_2 \sin \theta) \frac{r_1}{r_1} dq$$

$$= \frac{E_1 \cos \theta}{r_1} (R_2) \text{ and } r_1 \text{ (line)}$$

$$= E_1 \cos \theta (R_2 \cos \theta + R_2 \sin \theta) \text{ (r)}$$

$$\vec{E}_1 \text{ (outside)} = -E_1 \text{ (r)}$$

Max. deflection occurs when $\left| \frac{dF}{d\theta} \right|$ is
 zero, or when
 $\left| \frac{dF}{d\theta} \right| = \left| \frac{d}{d\theta} \left(\frac{E_1 R_2^2 \cos^2 \theta}{2} + \frac{E_1 R_2^2 \sin^2 \theta}{2} \right) \right| = 0$

Set $\frac{dF}{d\theta} = 0$ (no deflection, or field \vec{E})
 At $\theta = 90^\circ$, $\vec{E}_1 \perp \vec{r}_1$ (max), and $\vec{E}_1 \perp \vec{n}$ (min)

Ex. 13 $F = \frac{q^2}{4\pi \epsilon_0 r^2} = \frac{(2e)^2}{4\pi (8.85 \times 10^{-12}) r^2} = \frac{4e^2}{\pi \epsilon_0 r^2}$

$$F = 100 \times 10^{-20} \text{ N}, \quad r = 10^{-10} \text{ m}, \quad e = 1.6 \times 10^{-19} \text{ C}$$

$$e_1 = 2.16 \times 10^{-20} \text{ C}$$

Radius: $\text{rad} = 4\pi r^2 = 1.26 \times 10^{-19} \text{ m}^2$

Ex. 14 $W_C = \int_C \vec{E} \cdot d\vec{s}$

Assume a virtual displacement $\delta \vec{s}$, of the free wire.

$$W_C(\delta \vec{s}) = W_C(\vec{s}) + \int_C \vec{E} \cdot \delta \vec{s}$$

$$= W_C(\vec{s}) + \int_C E_r \delta s = C \int_C E_r \delta s$$

$$(C_r)_C = \frac{\partial W_C}{\partial s} = \frac{\partial}{\partial s} \int_C E_r \delta s = C \int_C E_r \delta s$$

is the direction of increasing s .

Chapter 7

Time-Varying Field and Maxwell's Equations

Ex. 1 $\nabla \times \mathbf{E} = -\dot{\mathbf{B}}$ $\Rightarrow \nabla \times (-\dot{\mathbf{A}}) = -\dot{\mathbf{B}}$ $\Rightarrow \nabla \times \mathbf{A} = \mathbf{B}$

Ex. 2 $\mathbf{B} = B_0 \cos(\omega t - \beta z) \hat{z}$
 $\int \mathbf{B} \cdot d\mathbf{l} = \int_0^{2\pi} B_0 \cos(\omega t - \beta z) \hat{z} \cdot \hat{\phi} r d\phi = 0$
 $\Rightarrow \nabla \times \mathbf{A} = \mathbf{B} = B_0 \cos(\omega t - \beta z) \hat{z}$
 $\Rightarrow \nabla \times \mathbf{A} = \mathbf{B} = B_0 \cos(\omega t - \beta z) \hat{z}$
 $\Rightarrow \nabla \times \mathbf{A} = \mathbf{B} = B_0 \cos(\omega t - \beta z) \hat{z}$

Ex. 3 In the rectangular loop with the assigned direction for \hat{z}

$$\oint \mathbf{E} \cdot d\mathbf{l} = \oint \mathbf{E} \cdot \hat{z} dz = 0 \quad (1)$$

where $\oint \mathbf{E} \cdot d\mathbf{l} = \int_0^L \mathbf{E} \cdot \hat{z} dz = \int_0^L E_z dz = E_z L$
 $\Rightarrow E_z = 0$ (2)

(3) At $t=0$, $\mathbf{E} = E_0 \hat{z}$ is applied and (2) becomes

$$E_0 = 0 \quad (3)$$

Solution of (3): $E = E_0 e^{-\beta z} \hat{z}$, $\beta = \omega/c$ (4)

At $t=0$, $\mathbf{E} = E_0 e^{-\beta z} \hat{z}$ when a negative step function $-E_0 e^{-\beta z}$ is applied. If $\mathbf{E} = E_0 \hat{z}$, then \mathbf{E} for $z > 0$ is the reverse of \mathbf{E} for $z < 0$.



(5) Energy dissipated in z
 $W = \int_0^L \mathbf{E} \cdot \hat{z} dz = \int_0^L E_0 e^{-\beta z} dz$
 $= \frac{1}{\beta} E_0 (1 - e^{-\beta L})$

$\frac{dI}{dt} = \frac{d}{dt} \left(\frac{2\pi r^2 \mu_0 n^2 I}{2\pi r} \right)$, $I = \frac{1}{2} B r$, $dr = \frac{1}{2} \frac{dB}{dt}$, $r = \frac{1}{2} (B r_0)$
 $\frac{dI}{dt} = \frac{2\pi r^2 \mu_0 n^2}{2\pi r} \frac{dB}{dt} \cdot \frac{1}{2} \frac{dB}{dt} = \frac{1}{2} \mu_0 n^2 \frac{dB^2}{dt}$
 $\frac{dI}{dt} = \frac{1}{2} \mu_0 n^2 \frac{dB^2}{dt}$
 $\frac{dI}{dt} = \frac{1}{2} \mu_0 n^2 \frac{dB^2}{dt}$
 $\frac{dI}{dt} = \frac{1}{2} \mu_0 n^2 \frac{dB^2}{dt}$



$\frac{dI}{dt} = \frac{1}{2} \mu_0 n^2 \frac{dB^2}{dt}$
 $\frac{dI}{dt} = \frac{1}{2} \mu_0 n^2 \frac{dB^2}{dt}$
 $\frac{dI}{dt} = \frac{1}{2} \mu_0 n^2 \frac{dB^2}{dt}$
 $\frac{dI}{dt} = \frac{1}{2} \mu_0 n^2 \frac{dB^2}{dt}$

Q.10 From Problem 9 above $\mathcal{E}_1 = \mu_0 n^2 a b \frac{dB}{dt}$

$\mathcal{E}_2 = \frac{1}{2} \mu_0 n^2 a b \frac{dB}{dt}$
 $\mathcal{E}_3 = \frac{1}{2} \mu_0 n^2 a b \frac{dB}{dt}$
 $\mathcal{E}_4 = \frac{1}{2} \mu_0 n^2 a b \frac{dB}{dt}$
 $\mathcal{E}_5 = \frac{1}{2} \mu_0 n^2 a b \frac{dB}{dt}$

Q.11 (a) Flux enclosed in the ring is $\Phi = \mu_0 n^2 \pi r^2 I$

The induced emf in the ring referring to the assigned direction for current is $\mathcal{E} = -\frac{d\Phi}{dt} = -\mu_0 n^2 \pi r^2 \frac{dI}{dt}$

Resistance of the circular ring $R = \frac{\rho l}{A}$

Combining (1) and (2) $i = \frac{\mathcal{E}}{R} = \frac{\mu_0 n^2 \pi r^2}{\rho l} \frac{dI}{dt}$

$i = \frac{\mu_0 n^2 \pi r^2}{\rho l} \frac{dI}{dt}$

$\int i dt = \frac{\mu_0 n^2 \pi r^2}{\rho l} \int \frac{dI}{dt} dt = \frac{\mu_0 n^2 \pi r^2}{\rho l} I$

$R_{eq} = \frac{\rho l}{\mu_0 n^2 \pi r^2}$

4) For 2 insulated elementary parts, each with an area $S = 2R^2 \sin^2 \theta = \pi R^2 \sin^2 \theta = \pi R^2 \frac{1}{2}$.

$$\text{Power loss in 2 elements } P' = 2 \left(\frac{1}{2} \pi R^2 \right) \left(\frac{1}{2} \pi R^2 \right) \int_0^{\pi/2} \sin^4 \theta \cos \theta d\theta = \frac{\pi^2}{4} R^4$$

$$P_{\text{loss}} = \frac{\pi^2}{4} R^4 \omega$$

Ex 2.12 $\vec{H}(t) = \vec{H}_0 \cos \omega t = -(\dot{P} \cos \omega t) = -\omega \int P \cos \omega t dt$
 $= -\frac{1}{\omega} \dot{P} \sin \omega t \quad (P = \tau I)$

$$I = -\frac{1}{\omega} \frac{dP}{dt} = -\frac{1}{\omega} \frac{d(\tau I)}{dt} = -\frac{\tau}{\omega} \frac{dI}{dt}$$

$$\Rightarrow -I = \frac{\tau}{\omega} \frac{dI}{dt} \Rightarrow \frac{dI}{I} = -\frac{\omega}{\tau} dt \Rightarrow I = I_0 e^{-\frac{\omega}{\tau} t}$$

Ex 2.13



Assuming the loop to have N turns each with an area each, the torque on the loop is \vec{T} with $\vec{T} = N \vec{\mu} \times \vec{B}$

Mechanical work done by the motor in rotating through an angle $d\theta$ is

$$dW_m = \tau d\theta = \mu B \sin \theta d\theta$$

Flux: Linking with the loop, $\vec{B} = \mu B \sin \theta$ and $\vec{I} = I \vec{a}$ (area vector in the loop), $\Phi = \int \vec{B} \cdot d\vec{a} = \mu B \int \sin \theta d\theta = \mu B a \cos \theta$

Electric energy required to send current I against this field is $dW_e = I d\Phi = I \mu B a \sin \theta d\theta = \mu B a I \sin \theta d\theta$

Ex 2.14 $d = \frac{dW}{dt} = \frac{1}{dt} \int \vec{J} \cdot d\vec{a} = \frac{1}{dt} \int \vec{J} \cdot \vec{a} \cos \theta d\theta$
 $= \frac{1}{dt} \int \vec{J} \cdot \vec{a} \cos \theta d\theta$

$\vec{J}_1 = \frac{1}{2} \vec{J}_0 \cos \theta$ (Current distributed in R_1)

On the other hand,

for R_2 side, $\vec{J}_2 = \frac{1}{2} \vec{J}_0 \sin \theta$, $\vec{J}_2 = \frac{1}{2} \vec{J}_0 \sin \theta \cos \theta$

for R_3 side, $\vec{J}_3 = \frac{1}{2} \vec{J}_0 \sin \theta$, $\vec{J}_3 = \frac{1}{2} \vec{J}_0 \sin \theta \cos \theta$

Mechanical power required to rotate \vec{a} is

$$P_m = \tau \omega = \frac{1}{2} (\vec{J}_1 \cdot \vec{J}_2 - \vec{J}_2 \cdot \vec{J}_3) = \frac{1}{2} \int \vec{J} \cdot \vec{a} \cos \theta d\theta = P_e$$

(Alternatively, $\vec{J}_1 = \vec{J}_2 = \vec{J}_3$ where $\vec{F} = \vec{J} \times \vec{B}$ is constant, and $dW = \vec{F} \cdot d\vec{a}$)

Beispiel 4) $\rho_1 = 1 + x_1$, $\rho_2 = 3 + 2x_1 + x_1^2$

$$\rho = \frac{\rho_1}{\rho_2} = \frac{1+x_1}{3+2x_1+x_1^2} \quad \rho_1 \rho_2 \rho = \rho_1 \frac{\rho_1}{\rho_2} = \frac{\rho_1^2}{\rho_2}$$

$$\begin{aligned} \text{d) } \rho_1^2 &= \rho^2 \rho_2 \rho_2 \rho_2 = \int_{-1}^1 (1+x_1)^2 (3+2x_1+x_1^2) dx \\ &= \int_{-1}^1 (1+2x_1+x_1^2)(3+2x_1+x_1^2) dx \\ &= \int_{-1}^1 (3+8x_1+7x_1^2+4x_1^3+x_1^4) dx \end{aligned}$$

$$\begin{aligned} \text{e) } \rho_1^2 &= \rho^2 \rho_2 = \frac{\rho_1^2}{\rho_2} = \frac{1+x_1}{3+2x_1+x_1^2} = \rho_1 \rho_2 \rho = \rho_1 \left(\frac{\rho_1}{\rho_2} \right) \rho_2 \\ \text{Erweitern mit } \rho_2 &= \int_{-1}^1 \rho_1 dx = \int_{-1}^1 (1+x_1) dx \\ &= 2 + x_1^2 \end{aligned}$$

$$\text{dabei ist } \rho_1 = 1+x_1, \quad \rho_2 = 3+2x_1+x_1^2, \quad \text{wobei } \rho = \frac{\rho_1}{\rho_2}$$

Beispiel 5) $\rho = 2 + x - \frac{x^2}{2} = 2 + x - \frac{x^2}{2}$ mit $\rho^2 = 2 + x - \frac{x^2}{2}$

$$\begin{aligned} \text{a) } \rho_1 (1-x) &= \rho_2 \rho = \rho_2 \left(2 + x - \frac{x^2}{2} \right) = 0 \\ \implies \rho_1 (2+x) &= \rho_2 \left(2 - \frac{x^2}{2} \right) = 0 \\ \implies \rho_1 &= \rho_2 \frac{2-x^2}{2+x} \end{aligned}$$

Beispiel 6) $\rho_1 = 2 + x$, $\rho_2 = 1 - x + \frac{x^2}{2}$ mit $\rho = \frac{\rho_1}{\rho_2} = 2 + x$

$$\rho_1 (1-x) = \rho_2 \rho_2 \rho_2 \quad \rho_1 = \rho_2 \rho_2 \rho_2 \quad \rho_1 = \rho_2 \rho_2 \rho_2 \quad \text{①}$$

$$\rho_1 (1-x) = \rho_2 \rho_2 \rho_2 \quad \rho_1 = \rho_2 \rho_2 \rho_2 \quad \rho_1 = \rho_2 \rho_2 \rho_2 \quad \text{②}$$

$$\rho_1 (1-x) = \rho_2 \rho_2 \rho_2 \quad \rho_1 = \rho_2 \rho_2 \rho_2 \quad \rho_1 = \rho_2 \rho_2 \rho_2 \quad \text{③}$$

$$\rho_1 (1-x) = \rho_2 \rho_2 \rho_2 \quad \rho_1 = \rho_2 \rho_2 \rho_2 \quad \rho_1 = \rho_2 \rho_2 \rho_2 \quad \text{④}$$

$$\rho_1 (1-x) = \rho_2 \rho_2 \rho_2 \quad \rho_1 = \rho_2 \rho_2 \rho_2 \quad \rho_1 = \rho_2 \rho_2 \rho_2 \quad \text{⑤}$$

$$\rho_1 (1-x) = \rho_2 \rho_2 \rho_2 \quad \rho_1 = \rho_2 \rho_2 \rho_2 \quad \rho_1 = \rho_2 \rho_2 \rho_2 \quad \text{⑥}$$

Beispiel 7) $\rho_1 = 1 - x$, $\rho_2 = 1 - x + \frac{x^2}{2}$

$$\text{a) } \rho_1 \rho_2 = \rho_1 \rho_2 \quad \rho_1 \rho_2 = \rho_1 \rho_2 \quad \rho_1 \rho_2 = \rho_1 \rho_2 \quad \text{①}$$

$$\rho_1 \rho_2 = \rho_1 \rho_2 \quad \rho_1 \rho_2 = \rho_1 \rho_2 \quad \rho_1 \rho_2 = \rho_1 \rho_2 \quad \text{②}$$

$$\rho_1 \rho_2 = \rho_1 \rho_2 \quad \rho_1 \rho_2 = \rho_1 \rho_2 \quad \rho_1 \rho_2 = \rho_1 \rho_2 \quad \text{③}$$

Ex-11: Median of two years.

Median 1: $\mu_1 = 10$, σ_1 must be such as that $\frac{10 - \mu_2}{\sigma_1} = 0$

$$\text{Standard deviation, } \mu_2 = 15, \sigma_2 = 5.$$

$$\mu_1 = \mu_2 + \sigma_2 \cdot (Z - 0) = 15$$

Ex-12: We will use joint PDF $f(x, y) = \frac{1}{2}xy$ for $x, y \in [0, 1]$. (1)

where $\int_0^1 \int_0^1 \frac{1}{2}xy \, dx \, dy = 1$ (2)

We need: $P(\frac{1}{2} < X < 1) = \int_{1/2}^1 \int_0^1 \frac{1}{2}xy \, dx \, dy$ (3)

(Formula: $P(X < x) = \int_0^x \int_0^y f(x, y) \, dx \, dy = \int_0^x \int_0^y \frac{1}{2}xy \, dx \, dy$)

Let $x = 1 - u$, $P(X < 1 - u) = \int_0^{1-u} \int_0^y \frac{1}{2}xy \, dx \, dy = \int_0^{1-u} \frac{1}{4}y^2 \, dy$ (4)

$P(\frac{1}{2} < X < 1) = 1 - P(X < \frac{1}{2}) = 1 - \int_0^{1/2} \frac{1}{4}y^2 \, dy$ (5)

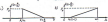
Substituting (4) in (5) $\Rightarrow P(\frac{1}{2} < X < 1) = 1 - \int_0^{1/2} \frac{1}{4}y^2 \, dy$ (6)

From (6) $P(X < 1) = \int_0^1 \frac{1}{4}y^2 \, dy = \int_0^1 \frac{1}{12} [y^3 - 0] \, dy$ (7)

$$= \frac{1}{12} [y^3]_0^1 = \frac{1}{12}$$

$$\therefore P(X < 1) = \frac{1}{12} = \frac{1}{12} \left[\int_0^1 \frac{1}{4}y^2 \, dy + \int_0^{1/2} \frac{1}{4}y^2 \, dy \right] = \frac{1}{12} \quad \text{Q.E.D.}$$

Ex-13 a)



Ex-13: $E(X) = \int_0^1 x \cdot f(x) \, dx = \int_0^1 x \cdot (2x) \, dx = \int_0^1 2x^2 \, dx = \frac{2}{3} [x^3]_0^1 = \frac{2}{3}$

$E(X^2) = \int_0^1 x^2 \cdot f(x) \, dx = \int_0^1 x^2 \cdot (2x) \, dx = \int_0^1 2x^3 \, dx = \frac{2}{4} [x^4]_0^1 = \frac{1}{2}$

Therefore: $E(X) = \frac{2}{3}$, $E(X^2) = \frac{1}{2}$

$$= \frac{2}{3} \left[\int_0^1 x \cdot (2x) \, dx \right] = \frac{2}{3} \left[\int_0^1 2x^2 \, dx \right] = \frac{2}{3} \left[\frac{2}{3} \right] = \frac{4}{9}$$

$$\therefore E(X) = \frac{2}{3}, \quad E(X^2) = \frac{1}{2} \quad \text{or} \quad \frac{3}{2}$$

$$\begin{aligned} \text{E11.13} \quad \Phi \cdot \mathcal{L} - \gamma \mu \frac{\partial^2 \Phi}{\partial x^2} &= 0 & \Phi \cdot \mathcal{H} = \mathcal{F} + \mu \frac{\partial \Phi}{\partial x} &= 0 \\ \Phi \cdot \mathcal{L} = \mathcal{F} & & \Phi \cdot \mathcal{H} = 0 & \end{aligned}$$

$$\mathcal{F} = 0: \quad \Phi \cdot \partial_x \mathcal{L} = \gamma \mu \frac{\partial^2 \Phi}{\partial x^2} (\mathcal{F} + \mathcal{G}) = \gamma \mu \frac{\partial^2 \Phi}{\partial x^2} (\mathcal{F} + \mu \frac{\partial \Phi}{\partial x}) = \mathcal{F} \mathcal{H} \mathcal{L} - \mathcal{G} \mathcal{L}$$

Wave equation for \mathcal{L} : $\mathcal{L}'' - \gamma \mu \frac{\partial^2 \mathcal{L}}{\partial x^2} = \mathcal{F} \mathcal{H} \mathcal{L}$

$$\mathcal{F} = 0: \quad \mathcal{L} \cdot \partial_x \mathcal{H} = \mathcal{L} \cdot \mathcal{F} + \mu \frac{\partial \mathcal{L}}{\partial x} (\mathcal{H} \mathcal{L} - \mathcal{L} \cdot \mathcal{F}) = \mu \frac{\partial \mathcal{L}}{\partial x} (\mathcal{H} \mathcal{L} - \mathcal{L} \cdot \mathcal{F})$$

Wave equation for \mathcal{L} : $\mathcal{L}'' - \gamma \mu \frac{\partial^2 \mathcal{L}}{\partial x^2} = -\mathcal{L} \cdot \mathcal{F}$

For standard time dependence: $\mathcal{L} \sim e^{-i\omega t}$, $\mathcal{H} \sim e^{-i\omega t}$

Multiplying equations: $\mathcal{L}'' \mathcal{L} = \mu \omega^2 \mathcal{L} = \gamma \mu \omega^2 \mathcal{L} + \mathcal{F} \mathcal{H} \mathcal{L}$

(for standard) $\mathcal{L}'' \mathcal{L} + \mu \omega^2 \mathcal{L} = -\mathcal{L} \cdot \mathcal{F}$

Ex11.14 $\mathcal{L} = \mathcal{L}_1$ as in Exercise 11.13 - part (a) (cont.)

Use phase: $\mathcal{H} = \gamma \frac{\partial \mathcal{L}}{\partial x} = \frac{\partial}{\partial x} [\mathcal{L}_1 \gamma \mu \frac{\partial \mathcal{L}_1}{\partial x} + \mathcal{L}_1 \gamma \mu \frac{\partial \mathcal{L}_1}{\partial x}]$

$$\mathcal{H} = \gamma \mu \frac{\partial}{\partial x} (\mathcal{L}_1 \cdot \mathcal{L}_1) = \gamma \mu \frac{\partial}{\partial x} (\mathcal{L}_1^2) = \mu \frac{\partial \mathcal{L}_1^2}{\partial x}$$

Phase term: $\mathcal{L} \cdot \mathcal{H} = \mathcal{L}_1 \cdot \mu \frac{\partial \mathcal{L}_1^2}{\partial x}$

Equating (1) and (2): $\mathcal{L}'' \mathcal{L}_1^2 + \mu \omega^2 \mathcal{L}_1^2 = \mu \mathcal{L}_1 \frac{\partial \mathcal{L}_1^2}{\partial x}$

From (2): $\mathcal{H} = \mu \frac{\partial \mathcal{L}_1^2}{\partial x}$
 $= \mu \frac{\partial \mathcal{L}_1^2}{\partial x} \frac{\partial \mathcal{L}_1}{\partial x} \frac{\partial \mathcal{L}_1}{\partial x} = \mu \frac{\partial \mathcal{L}_1^2}{\partial x} \frac{\partial \mathcal{L}_1}{\partial x} \frac{\partial \mathcal{L}_1}{\partial x}$

Ex11.14 $\mathcal{L} = \mathcal{L}_1$ as in Exercise 11.13 - part (b) (cont.)

Phase: $\mathcal{H} = \mathcal{L}_1 \cdot \mathcal{L}_1 = \mathcal{L}_1^2$

Similar to Problem 1: $\mathcal{L}'' \mathcal{L}_1^2 + \mu \omega^2 \mathcal{L}_1^2 = \mu \frac{\partial \mathcal{L}_1^2}{\partial x} \frac{\partial \mathcal{L}_1}{\partial x}$

$$\mathcal{L} = \frac{1}{\gamma \mu} \mathcal{H} \cdot \mathcal{L}_1 = \frac{1}{\gamma \mu} \mathcal{L}_1^2 \cdot \mathcal{L}_1 = \frac{1}{\gamma \mu} \mathcal{L}_1^3$$

$$\mathcal{L} \cdot \mathcal{H} = \frac{1}{\gamma \mu} \mathcal{L}_1^3 \cdot \mathcal{L}_1^2 = \frac{1}{\gamma \mu} \mathcal{L}_1^5$$

Ex. 21 Use polar coordinates: $E = \mathbb{R}_+ \times \frac{d\Omega}{d\Omega} \times \mathbb{R} \times \mathbb{R} \times \mathbb{R} \times \mathbb{R}$
 $\mathcal{P} \circ E = \mathbb{R}_+ \times \frac{d\Omega}{d\Omega} \times \frac{d\Omega}{d\Omega} \times \mathbb{R} \times \mathbb{R} \times \mathbb{R} \times \mathbb{R} \times \mathbb{R} \times \mathbb{R} \times \mathbb{R}$
 $\omega = \text{proj}_{\mathbb{R}^2} \mathcal{P} \rightarrow \mathcal{P} = \mathbb{R}_+ \times \frac{d\Omega}{d\Omega} \times \text{sing. points}$

In four space, $\mathcal{P} = \text{proj}_{\mathbb{R}^2} \mathcal{P} \rightarrow \mathcal{P} = \mathbb{R}_+ \times \frac{d\Omega}{d\Omega} \times \text{sing. points}$
 $\text{Sing. points} = \mathbb{R}_+ \times \frac{d\Omega}{d\Omega} \times \text{sing. points} \times \text{sing. points}$

Ex. 22 Maxwell's curl eqs: $\mathcal{P} \circ E = -\text{grad} \mathcal{P}$ (1)
 $\mathcal{P} \circ \mathcal{P} = \text{grad} \mathcal{P}$ (2)

From $\mathcal{P} \circ E = 0$, define \mathcal{L}_1 such that $\mathcal{L}_1 \circ \mathcal{P} \circ \mathcal{L}_1$.
 From (1), $\mathcal{P} = \frac{1}{\mathcal{L}_1} \mathcal{P} \circ \mathcal{L}_1 = \frac{1}{\mathcal{L}_1} \mathcal{P} \circ \mathcal{P} \circ \mathcal{L}_1$
 $= \frac{1}{\mathcal{L}_1} [\mathcal{P}(\mathcal{P} \circ \mathcal{L}_1) - \mathcal{P} \circ \mathcal{L}_1]$ (3)

From (2), $\mathcal{P} \circ (\mathcal{P} \circ \text{grad} \mathcal{L}_1) = 0$. Let $\mathcal{L}_2 = \text{grad} \mathcal{L}_1 = -\mathcal{P} \circ \mathcal{L}_1$. (4)
 Subtracting (3) from (4): $\omega \mathcal{L}_2 = \frac{1}{\mathcal{L}_1} [\mathcal{P}(\mathcal{P} \circ \mathcal{L}_1) - \mathcal{P} \circ \mathcal{L}_1] - \mathcal{P} \circ \mathcal{L}_1$
 Choose $\mathcal{P} \circ \mathcal{L}_1 = \text{grad} \mathcal{L}_2$. (5)

On \mathcal{L}_1 , (3) becomes $\mathcal{L}_2 = \text{grad} \mathcal{L}_2 = \frac{1}{\mathcal{L}_1} \mathcal{P}(\mathcal{P} \circ \mathcal{L}_1)$.
 On \mathcal{L}_2 , (4) becomes $\mathcal{P} \circ \mathcal{L}_2 = \text{grad} \mathcal{L}_2 = 0$, a homogeneous differential eq.

Ex. 23 $\mathcal{P} = \text{grad} \mathcal{P} \circ \mathcal{L}_1$ (6)
 $\mathcal{P} \circ \mathcal{L}_1 = -\text{grad} \mathcal{P} \circ \mathcal{L}_1 = -\text{grad} \mathcal{P} \circ \mathcal{L}_1$ (7)
 $\rightarrow \mathcal{P} \circ \mathcal{L}_1 (\mathcal{L}_1 - \mathcal{L}_1^2) \mathcal{L}_1 = 0$. Let $\mathcal{L}_2 = \mathcal{L}_1^2 \mathcal{L}_1 = \mathcal{P} \circ \mathcal{L}_1$. (8)
 $\mathcal{P} \circ \mathcal{L}_2 = \text{grad} \mathcal{P} \circ \mathcal{L}_2 = \text{grad} \mathcal{P} \circ \mathcal{L}_1 \circ \mathcal{L}_1 = \text{grad} \mathcal{P} (\mathcal{L}_1 - \mathcal{L}_1^2)$ (9)

Substituting (8) and (9) in (6):
 $\text{grad} \mathcal{P} \circ \mathcal{P} \circ \mathcal{L}_1 = \text{grad} \mathcal{P} (\mathcal{L}_1^2 \mathcal{L}_1 + \mathcal{P} \circ \mathcal{L}_1 - \mathcal{L}_1^2)$
 $= \text{grad} \mathcal{P} (\mathcal{P} \circ \mathcal{L}_1 - \mathcal{P} \circ \mathcal{L}_1)$ (10)

Choose $\mathcal{P} \circ \mathcal{L}_1 = \mathcal{L}_2$. Eq (6) becomes
 $\mathcal{L}_2 \circ \mathcal{P} \circ \mathcal{L}_2 = \mathcal{L}_2 \circ \mathcal{L}_2 = -\frac{1}{\mathcal{L}_2}$ (11)

① If $\text{Im} \mathbb{E}$ becomes

$$\mathbb{E} = \zeta \mathbb{E}_0 + \mathbb{P} \mathbb{P} - \mathbb{E}_0$$

$$= \zeta_0^2 \mathbb{E}_0 = (\mathbb{P}^* \mathbb{E}_0 + \mathbb{P} \mathbb{P} \mathbb{E}_0).$$

②

Combination of Eqs. (1) and (2) gives

$$\mathbb{E} = \mathbb{P} \cdot \mathbb{P} \cdot \mathbb{E}_0 = \frac{\mathbb{E}_0}{\zeta}.$$

Ex. 7.14

$$\text{①} \quad \left| \frac{\text{Transmission current}}{\text{Excitation current}} \right| = \frac{I_{21}}{I_1} = \frac{I_{21} \cos \theta_2 \sin \theta_1}{I_1 \sin \theta_1 \cos \theta_2}$$

$$= \frac{I_{21}}{I_1} = 10^{-1}.$$

② In a source-free conductor:

$$\nabla \times \mathbb{H} = \sigma \mathbb{E}, \quad \text{③}$$

$$\nabla \cdot \mathbb{E} = \rho = j\omega \mu \mathbb{H}, \quad \text{④}$$

$$\nabla \times \text{③} \Rightarrow \nabla \times \nabla \times \mathbb{H} = \sigma (\nabla \times \mathbb{E}) = \sigma \nabla \mathbb{H} = \sigma \nabla \cdot \mathbb{E}, \quad \text{⑤}$$

But $\nabla \cdot \mathbb{H} = 0$. If $\text{Im} \mathbb{E}$ becomes

$$\nabla^2 \mathbb{E} = \sigma \nabla \times \mathbb{E} = 0 \quad \text{⑥}$$

Combining ⑤ and ⑥

$$\nabla^2 \mathbb{H} - \mu \sigma \nabla \times \mathbb{H} = 0.$$